

Incorporation of Half-Cycle Theory Into Ko Aging Theory for Aerostructural Flight-Life Predictions

William L. Ko, Van T. Tran, and Tony Chen NASA Dryden Flight Research Center Edwards, California



NASA STI Program ... in Profile

Since its founding, NASA has been dedicated to the advancement of aeronautics and space science. The NASA scientific and technical information (STI) program plays a key part in helping NASA maintain this important role.

The NASA STI program is operated under the auspices of the Agency Chief Information Officer. It collects, organizes, provides for archiving, and disseminates NASA's STI. The NASA STI program provides access to the NASA Aeronautics and Space Database and its public interface, the NASA Technical Report Server, thus providing one of the largest collections of aeronautical and space science STI in the world. Results are published in both non-NASA channels and by NASA in the NASA STI Report Series, which includes the following report types:

- TECHNICAL PUBLICATION. Reports of completed research or a major significant phase of research that present the results of NASA programs and include extensive data or theoretical analysis. Includes compilations of significant scientific and technical data and information deemed to be of continuing reference value. NASA counterpart of peer-reviewed formal professional papers but has less stringent limitations on manuscript length and extent of graphic presentations.
- TECHNICAL MEMORANDUM. Scientific and technical findings that are preliminary or of specialized interest, e.g., quick release reports, working papers, and bibliographies that contain minimal annotation. Does not contain extensive analysis.
- CONTRACTOR REPORT. Scientific and technical findings by NASA-sponsored contractors and grantees.

- CONFERENCE PUBLICATION. Collected papers from scientific and technical conferences, symposia, seminars, or other meetings sponsored or cosponsored by NASA.
- SPECIAL PUBLICATION. Scientific, technical, or historical information from NASA programs, projects, and missions, often concerned with subjects having substantial public interest.
- TECHNICAL TRANSLATION. Englishlanguage translations of foreign scientific and technical material pertinent to NASA's mission.

Specialized services also include creating custom thesauri, building customized databases, and organizing and publishing research results.

For more information about the NASA STI program, see the following:

Access the NASA STI program home page at http://www.sti.nasa.gov.

- E-mail your question via the Internet to help@sti.nasa.gov.
- Fax your question to the NASA STI Help Desk at (301) 621-0134.
- Phone the NASA STI Help Desk at (301) 621-0390.
- Write to:
 NASA STI Help Desk
 NASA Center for AeroSpace Information
 7121 Standard Drive
 Hanover, MD 21076-1320

NASA/TP-2007-214608



Incorporation of Half-Cycle Theory Into Ko Aging Theory for Aerostructural Flight-Life Predictions

William L. Ko, Van T. Tran, and Tony Chen NASA Dryden Flight Research Center Edwards, California

National Aeronautics and Space Administration

Dryden Flight Research Center Edwards, California 93523-0273

Cover art: NASA Dryden Flight Research Center, photograph EC04-0029-17.
NOTICE Use of trade names or names of manufacturers in this document does not constitute an official endorsement of such products or manufacturers, either expressed or implied, by the National Aeronautics and Space Administration.
Available from: NASA Center for AeroSpace Information 7115 Standard Drive Hanover, MD 21076-1320 (301) 621-0390

CONTENTS

ABSTRACT
NOMENCLATURE
INTRODUCTION4
THE B-52B AIRPLANE CARRYING THE HYPER-X LAUNCH VEHICLE 5
THE KO CLOSED-FORM AGING THEORY5Failure-Critical Structural Components5Stress/Load Equation6Operational Load Factor6Crack Size Determinations7The Ko Operational Life Equation8The Ko Operational Life Theory Flow Chart9
HALF-CYCLE CRACK GROWTH THEORY 10 The Walker Crack Growth Equation 10 The Half-Cycle Crack Growth Equation 11
CRACK GROWTH COMPUTER PROGRAM. 12
OPERATIONAL LIFE ANALYSIS14The B-52B and Pegasus Pylon Hooks14Flight Load Spectra15Crack Growth Calculations15Number of Operational Flights16
RESULTS
CONCLUSIONS
APPENDIX A - OPERATIONAL LIFE EQUATIONS
APPENDIX B - CRACK GROWTH COMPUTER PROGRAM
APPENDIX C - MATERIAL PROPERTIES

FIGURES	 		 	6									
REFERENCES													8

ABSTRACT

The half-cycle crack growth theory was incorporated into the Ko closed-form aging theory to improve accuracy in the predictions of operational flight life of failure-critical aerostructural components. A new crack growth computer program was written for reading the maximum and minimum loads of each half-cycle from the random loading spectra for crack growth calculations and generation of in-flight crack growth curves. The unified theories were then applied to calculate the number of flights (operational life) permitted for B-52B pylon hooks and Pegasus[®] adapter pylon hooks to carry the Hyper-X launching vehicle that air launches the X-43 Hyper-X research vehicle. A crack growth curve for each hook was generated for visual observation of the crack growth behavior during the entire air-launching or captive flight. It was found that taxiing and the takeoff run induced a major portion of the total crack growth per flight. The operational life theory presented can be applied to estimate the service life of any failure-critical structural components.

NOMENCLATURE

\boldsymbol{A}	crack location parameter ($A = 1.12$ for a surface or edge crack)
a	depth (crack size) of semi-elliptic surface crack, in
a_{i-1}	crack size at the end of the $(i-1)$ -th half cycle, in
a_c^o	operational (final) crack size associated with operational
	load V_{max}^o , in, $=\frac{Q}{\pi} \left(\frac{K_{IC}}{AM_k f \sigma^*} \right)^2 = \frac{a_c^p}{f^2}$
a_c^p	proof (initial) crack size associated with proof load V^* , in, $=\frac{Q}{\pi} \left(\frac{K_{IC}}{\Delta M_{VC} \sigma^*} \right)^2$
a_1	crack size at the end of the first flight, in, $= a_c^p + \Delta a_1$
C	coefficient of Walker crack growth equation, $\frac{\text{in}}{\text{cycle}} \left(\text{ksi} \sqrt{\text{in}} \right)^{-m}$
c	half length of semi-elliptic surface crack, in
E(k)	complete elliptic function of the second kind, $=\int_0^{\pi/2} \sqrt{1-k^2 \sin^2 \phi} d\phi$
F_1^*	number of operational flights based on the first fight load data
f	operational load factor associated with the worst half cycle of random load
	spectrum, $=\frac{V_{max}^o}{V^*} = \frac{\sigma_{max}^o}{\sigma^*} = \sqrt{\frac{a_c^p}{a_c^o}}$
HXLV	Hyper-X launch vehicle

h thickness of hook, in K_{IC} mode I critical stress intensity factor, ksi $\sqrt{\text{in}}$

 $K_{
m max}$ mode I stress intensity factor associated with $\sigma_{
m max}$, ksi $\sqrt{
m in}$

 ΔK mode I stress intensity amplitude associated with stress amplitude, ($\sigma_{\rm max} - \sigma_{\rm min}$), ksi $\sqrt{\rm in}$

 $(K_{\text{max}})_i$ mode I stress intensity factor associated with $(\sigma_{\text{max}})_i$ of *i*-th half cycle, ksi $\sqrt{\text{in}}$ ΔK_i mode I stress intensity amplitude associated $[(\sigma_{\max})_i - (\sigma_{\min})_i]$ of *i*-th half cycle, ksi √in i $1, 2, 3, \dots$, integer associated with the *i*-th half cycle $1, 2, 3, \dots$, integer associated with the j-th half cycle, or the j-th flight j modulus of elliptic function, = $\sqrt{1 - \left(\frac{a}{c}\right)^2}$ k flaw magnification factor ($M_k = 1$ for a shallow crack) M_k Walker stress intensity factor exponent associated with $(K_{\text{max}})^m$ mnumber of stress cycles generated during the first flight N_1 N partial stress cycles during flight (fraction of N_1) Walker stress-ratio exponent associated with $(1-R)^n$ nsurface flaw and plasticity factor, = $[E(k)]^2 - 0.212 \left(\frac{\sigma^*}{\sigma_Y}\right)^2$ Qstress ratio associated with constant amplitude load cycle, = $\frac{\sigma_{min}}{\sigma_{min}}$ R stress (or load) ratio associated with the worst half-cycle, $=\frac{\sigma_{\min}^o}{\sigma_{\max}^o} = \frac{V_{\min}^o}{V_{\max}^o}$ R^{o} stress ratio associated with the *i*-th half cycle, $=\frac{(\sigma_{\min})_i}{(\sigma_{\max})_i}$ R_i SRB/DTV solid rocket booster drop test vehicle V_A B-52B pylon front hook load, lb V_{BL} B-52B pylon left rear hook load. lb V_{BR} B-52B pylon right rear hook load, lb V_{PFL} Pegasus pylon front left hook load, lb V_{PFR} Pegasus pylon front right hook load, lb V_{PRL} Pegasus pylon rear left hook load, lb V_{PRR} Pegasus pylon rear right hook load, lb VA B-52B pylon front hook **VBL** B-52B pylon left rear hook **VBR** B-52B pylon right rear hook **VPFL** Pegasus pylon front left hook **VPFR** Pegasus pylon front right hook **VPRL** Pegasus pylon rear left hook **VPRR** Pegasus pylon rear right hook

V applied hook load, lb

 V^* proof load for any hook, lb

 V_{\max}^o maximum load of the worst cycle of random load spectrum, lb V_{\min}^o minimum load of the worst cycle of random load spectrum, lb Δa_1 amount of crack growth induced at the end of the first flight, in

 Δa amount of a partial crack growth at any time step during the flight, in

 δa_i crack growth increment induced by the *i*-th half cycle, in

 η stress/load coefficient, ksi/lb

 σ^* tangential stress at critical stress point induced by the proof load V^* , ksi, = ηV^*

 σ_A tangential stress at critical stress point of B-52B pylon front hook induced by V_A ,

ksi

 σ_{BL} tangential stress at critical stress point of B-52B pylon rear left hook induced by

 V_{BL} , ksi

 σ_{BR} tangential stress at critical stress point of B-52B pylon rear right hook induced by

 V_{BR} , ksi

 σ_{PFL} tangential stress at critical stress point of Pegasus pylon front left hook induced by

 V_{PFL} , ksi

 σ_{PFR} tangential stress at critical stress point of Pegasus pylon front right hook induced

by V_{PFR} , ksi

 σ_{PRL} tangential stress at critical stress point of Pegasus pylon rear left hook induced by

 V_{PRL} , ksi

 σ_{PRR} tangential stress at critical stress point of Pegasus pylon rear right hook induced by

 V_{PRR} , ksi

 $\sigma_{\rm max}^o$ tangential stress at critical stress point associated with operational peak load,

 $V_{\rm max}^o$, ksi

 σ_U ultimate tensile stress, ksi

 σ_Y yield stress, ksi

 σ_{\max} maximum stress of constant amplitude loading cycles, ksi minimum stress of constant amplitude loading cycles, ksi

 σ_t tangential stress along hook inner boundary, ksi

 $(\sigma_t)_{\text{max}}$ maximum value of σ_t at the stress critical point, ksi

 au_U ultimate shear stress, ksi

 ϕ angular coordinate for semi-elliptic surface crack, rad

 θ_c angular location of critical stress point, deg

(); quantity associated with the *i*-th half cycle of random loading spectrum

()* quantity associated with proof load

INTRODUCTION

The NASA Dryden B-52B (McDonnell Douglas, St. Louis, Missouri) launch airplane has been used to carry various types of flight research vehicles for high-altitude air-launching tests. The test vehicle is mated to the B-52B pylon through one L-shaped front hook and two identical L-shaped rear hooks. The L-shaped structural geometry will always induce tensile or compressive stress concentration depending on the loading direction (B-52 hooks can have only tensile stress concentrations). The inner curved boundary point of the hook where the tangential tensile stress reaches a maximum is called a critical stress point of the hook and is the potential fatigue crack initiation site.

During the early stages of the flight tests of the solid rocket booster drop test vehicle (SRB/DTV, 49,000 lb) (1983), the two old rear hooks (fabricated with 4340 steel) failed almost simultaneously during towing of the B-52B airplane carrying the SRB/DTV on a relatively smooth taxiway (low-amplitude dynamic loading). A microsurface crack at the critical stress point of each hook escaped detection because of surface masking by plating films. Those fatigue cracks could have been initiated from the past long period of flight test load cycling and the surface corrosion. If the hook failures had occurred during a takeoff run or during captive flight, a catastrophic accident might have occurred. This type of potential accident underscored the need for reliable and accurate calculations of the fatigue crack growths, which could thereby estimate the safe operational flight life of the hooks for each new flight test program.

Recently, the B-52B airplane has been used to carry the Hyper-X launching vehicle that airlaunches the X-43 hypersonic flight research vehicle for Mach 7–10 flight tests. The B-52B pylon hooks were intended to carry the total store weight of 40,000 lb (slightly lighter than the SRB/DTV weight 49,000 lb).

The safety of flight tests using B-52B pylon hooks to carry any drop-test vehicle [for example, the Hyper-X launching vehicle (HXLV)] hinges upon the structural integrity of the failure-critical structural components like B-52B pylon hooks and Pegasus® (Orbital Sciences Corporation, Dulles, Virginia) pylon hooks. It is, therefore, of vital importance to accurately determine the safe operational flight life for each of those failure-critical aerostructural components.

Earlier, Ko (refs. 1–6) developed several aging theories for predicting the operational flight life of airborne failure-critical structural components. The most accurate aging theory developed to date was the Ko closed-form aging theory (refs. 5, 6). In this report, the half-cycle crack growth theory will be incorporated into the Ko closed-form aging theory (refs. 5, 6) to improve the accuracy of operational life predictions of failure-critical airborne structural components. A special half-cycle crack growth computer program was written to calculate the crack growth needed for operational life predictions. The enhanced Ko closed-form aging theory was then applied to calculate the number of safe flights permitted for B-52B pylon hooks and Pegasus adapter pylon hooks to carry the HXLV for air-launching the X-43 hypersonic flight research vehicle.

The operational life theory presented in this report can also be applied to estimate the service life of any failure-critical structural components.

THE B-52B AIRPLANE CARRYING THE HYPER-X LAUNCH VEHICLE

Figure 1 shows the B-52B aircraft carrying the HXLV with the X-43 hypersonic flight research vehicle mated to its nose for air-launching flight tests at Mach 7–10. Because the Pegasus booster rocket has a delta wing which prevents the cylindrical booster body to nest closely under the B-52B pylon concave belly, a special adapter called the Pegasus adapter pylon (weighing 2,300 lb) is used to link the B-52B pylon hooks to the HXLV (weighing 37,700 lb). The Hyper-X launch vehicle is carried by the four identical Pegasus adapter pylon hooks, and the Pegasus adapter pylon is, in turn, carried by the B-52B pylon hooks using a double-shear pin to link to the front hook and through the Pegasus pylon adapter-shackles to connect to the two rear hooks of the B-52B pylon. The total weight then carried by the B-52B pylon hooks is 40,000 lb.

The double-shear pin is not fatigue-critical because there is no stress concentration problem. The two Pegasus pylon adapter shackles, however, are highly failure-critical because each shackle contains a rectangular hole with four, sharp, rounded corners in the upper part, and a circular hole in the lower part (ref. 8). Other failure-critical structural components identified are: the L-shaped B-52B front and two rear hooks and the four, identical L-shaped, Pegasus adapter pylon hooks (ref. 8).

The operational flight-life of all the pylon hooks will be analyzed because the actual loading spectra for those components are now available for the application of the half-cycle crack growth theory. The un-instrumented Pegasus adapter shackles were not analyzed because the actual loading spectra do not exist.

THE KO CLOSED-FORM AGING THEORY

The following section will describe the Ko closed-form aging theory. In the formulation of the Ko closed-form aging theory for aerostructural operational life predictions, the following steps are used.

Failure-Critical Structural Components

Acomplex structure usually contains a certain number of failure-critical structural components, each of which contains a critical stress point. The critical stress point is a boundary point of the structural component where the tangential tensile stress concentration reaches a maximum, and is the potential fatigue crack initiation site. The operational life of the complex structure is then determined by the operational life of the worst failure-critical structural component having the shortest fatigue life (that is, the fastest crack growth rate at the critical stress point). Therefore, in the operational life analysis, the failure-critical structural components must be identified and their stress fields established.

Stress/Load Equation

In the actual flight tests, the strain gages are usually installed in the vicinity of the critical stress point, and are calibrated to record the applied load (such as hook load). After the failure-critical structural components are identified, stress analysis must be performed for each critical structural component to establish the functional relationship between the applied load and the induced tangential stress at the critical stress point (refs. 7–9). For example, if V^* is the proof load, and if σ^* is the induced proof stress at the stress critical point, then the proof stress, σ^* , may be related to the proof load, V^* , through the following stress/load functional relationship in equation (1)

$$\sigma^* = \eta V^* \tag{1}$$

where η is defined as the stress/load coefficient, and is determined from the finite-element stress analysis of the critical structural component (refs. 7–9).

Operational Load Factor

The next information needed in the operational life analysis is the operational load factor, f (<1), defined in equation (2) as

$$f = \frac{\sigma_{max}^o}{\sigma^*} = \frac{V_{max}^o}{V^*} < 1 \tag{2}$$

where σ_{\max}^o is the operational maximum stress at the critical stress point induced by the operational maximum load, V_{\max}^o , of the worst half-cycle of the random loading spectrum. The worst half-cycle is defined as the half-cycle with the maximum stress (load) amplitude, associated with the minimum stress ratio or load ratio as shown in equation (3)

$$(\sigma_{\max}^o - \sigma_{\min}^o) = \sigma_{\max}^o (1 - R^o) = \text{Maximum} \quad ; \quad R^o = \frac{\sigma_{\min}^o}{\sigma_{\max}^o} = \frac{V_{\min}^o}{V_{\max}^o} = \text{Minimum}$$
 (3)

where R^o is the stress (or load) ratio associated with the worst half-cycle. The worst half-cycle is to be searched out in light of condition (3) by means of a special load-factor-searching computer code embedded in the newly written crack growth computer program discussed in Appendix B. Keep in mind that the value of $V_{\rm max}^o$ may not necessarily be the peak load of the entire flight-loading spectrum. Past flight load data showed that the operational maximum load, $V_{\rm max}^o$, usually occurred during the takeoff run because the ground effect induced the maximum crack growth rate.

Crack Size Determinations

In developing the Ko aging theory (refs. 5, 6), the proof (initial) and operational (final) crack sizes $\{a_c^p, a_c^o\}$ at the critical stress point of the failure-critical structural component must be established first. The two crack sizes $\{a_c^p, a_c^o\}$ are associated respectively with the proof and operational stresses $\{\sigma^*, \sigma_{\text{max}}^o\}$ [or proof and operational peak loads $\{V^*, V_{\text{max}}^o\}$], and are to be calculated from crack tip equations (4) and (5) based on the fracture mechanics (refs 1–4).

$$a_C^P = \frac{Q}{\pi} \left(\frac{K_{IC}}{AM_k \sigma^*} \right)^2 = \frac{Q}{\pi} \left(\frac{K_{IC}}{AM_k \eta V^*} \right)^2 \tag{4}$$

$$a_c^o = \frac{Q}{\pi} \left(\frac{K_{IC}}{AM_k \sigma_{max}^o} \right)^2 = \frac{Q}{\pi} \left(\frac{K_{IC}}{AM_k f \eta V^*} \right)^2 = \frac{a_c^p}{f^2}$$
 (5)

In equations (4) and (5), K_{IC} is the mode I critical stress intensity factor (material dependent), A is the crack location parameter (for a surface crack, A = 1.12, refs. 1–4), M_k is the flaw magnification factor (for a shallow surface crack, $M_k = 1$, refs. 1–4), and finally, Q is the surface flaw shape and plasticity factor. For an elliptic surface crack (surface length 2c, depth a), Q may be expressed as in equation (6) (refs. 1–4):

$$Q = [E(k)]^2 - 0.212 \left(\frac{\sigma^*}{\sigma_Y}\right)^2 \tag{6}$$

In equation (6), σ_Y is the yield stress, and E(k) is the complete elliptic function of the second kind defined in equation (7)

$$E(k) = \int_0^{\pi/2} \sqrt{1 - k^2 \sin^2 \phi} d\phi$$
 (7)

where ϕ is the angular coordinate for a semi-elliptic surface crack, seen in fig. 2 (refs. 1–4), and k is the modulus of the elliptic function defined in equation (8)

$$k = \sqrt{1 - \left(\frac{a}{c}\right)^2} \tag{8}$$

Table 1 lists the input data for finding the values of E(k) from the complete elliptic integral table (ref. 10) for different crack aspect ratios a/2c. The values of Q were then calculated from equation (6). Table 1 lists only typical values of Q calculated for the worst stress ratio $\sigma^*/\sigma_Y = 1$.

a/2c	a/c	$k = \sqrt{1 - \left(a/c\right)^2}$	$\sin^{-1} k$, deg.	<i>E</i> (<i>k</i>)*	Q
0.1	0.2	0.979796	78.463041	1.0506	0.8918
0.2	0.4	0.916515	66.421822	1.1584	1.1299
0.25	0.5	0.866025	60.0	1.2111	1.2548
0.3	0.6	0.8	53.130102	1.2764	1.4172
0.4	0.8	0.6	36.869898	1.4181	1.7990
0.5	1.0	0.0	0.0	$\pi/2$	2.2554

Table 1. Key data for the calculations of Q, equation (6); $\sigma^*/\sigma_Y = 1$.

Figure 2 shows the value of Q plotted as a function of crack aspect ratio a/2c with stress ratio σ^*/σ_Y as a parameter. Remember that the values $\{a/2c = 0.25, a/2c = 0.5\}$ listed in table 1 are respectively the aspect ratios of the actual initial surface cracks of the failed B-52B pylon old rear left and right hooks (ref. 7).

The Ko Operational Life Equation

This section describes the basics of the Ko closed-form operational life equations (refs. 5, 6). In the formulation of Ko operational life equations, it was assumed that all the flights last for the same duration of time and induce identical random loading spectra. By representing the random loading spectra with the equivalent-constant-amplitude loading spectra so that the Walker crack growth equation (refs. 3, 4) may be applied, Ko (refs. 5, 6) formulated the closed-form operational life equation (as seen in equation (9) and derived in Appendix A) for the calculations of the number of flights, F_1^* , permitted for each failure-critical aerostructural component.

$$F_1^* = \frac{(a_c^p)^{1 - \frac{m}{2}} - (a_c^o)^{1 - \frac{m}{2}}}{(a_c^p)^{1 - \frac{m}{2}} - (a_1)^{1 - \frac{m}{2}}} = \frac{1 - f^{m - 2}}{1 - \left(1 + \frac{\Delta a_1}{a_c^p}\right)^{1 - \frac{m}{2}}} \quad ; \quad a_1 = a_c^p + \Delta a_1$$

$$(9)$$

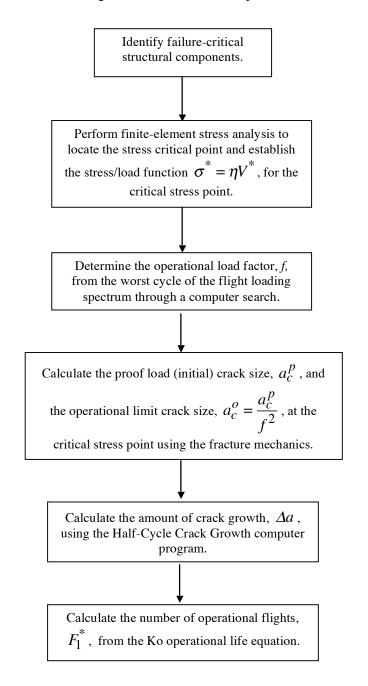
In equation (9), $a_1 (= a_c^p + \Delta a_1)$ is the crack size at the end of the first flight, and Δa_1 is the amount of crack growth induced by the first flight.

In equation (9), the known quantities are: the Walker stress-intensity-factor exponent m (refs. 3, 4), the load factor f [determined from equation (2)], and the proof (initial) and operational (final) crack sizes { a_c^p , a_c^o } [calculated respectively from equations {(4), (5)}]. The only unknown is the crack growth, Δa_1 , induced by the first flight. Therefore, the accuracy of the predicted operational flight life, F_1^* , from equation (9) is hinged upon the method of calculations used in determining the

^{*} Obtained from the complete elliptic integral table (ref. 10).

crack growth, Δa_1 . The step-by-step processes required to use the Ko operational life equation (9) are shown in the following flow chart.

The Ko Operational Life Theory Flow Chart



HALF-CYCLE CRACK GROWTH THEORY

In the calculations of fatigue crack growth under random loading, there are several existing methods (ref. 11). For example,

- 1) Peak count method
- 2) Mean crossing peak count method
- 3) Range count method
- 4) Range-mean count method
- 5) Range pair count method
- 6) Level-crossing count method, and
- 7) Half-cycle method, etc. (ref. 11).

After reviewing the basics of those different theories, the half-cycle theory was chosen for the present crack growth calculations. The reason being that the half-cycle theory accounts every half-cycle of the random load spectrum without missing any secondary, small-amplitude half-cycles which do not even cross over the mean stress line (ref. 2). The second reason is that the predictions of fatigue life from the half-cycle theory compare fairly well with some existing experimental fatigue data (ref.11, pg. 211, ref. 12).

The half-cycle theory assumes that the amount of crack growth induced by each half-cycle of the random loading spectrum is considered as one-half of a complete cycle of a constant amplitude load spectrum with the same load amplitude. Figure 3 shows the resolutions of the random stress cycles into a series of half-cycles with different loading amplitudes (ref. 2). Under such assumption, the Walker crack growth equation may be used to calculate the incremental crack growth induced by each half-cycle with particular load amplitude.

The Walker Crack Growth Equation

The Walker crack-growth equation for the constant amplitude load spectrum is given in equation (10) by

$$\frac{da}{dN} = C(K_{max})^m (1 - R)^n = C(\Delta K)^m (1 - R)^{n - m}$$
(10)

where C, m, n are material constants. The mode I stress intensity factor, K_{max} , mode I stress intensity amplitude, ΔK , and the stress ratio, R are defined in equations (11), (12), and (13).

$$K_{\text{max}} = AM_k \sigma_{\text{max}} \sqrt{\frac{\pi a}{Q}}$$
 (11)

$$\Delta K = AM_k (\sigma_{\text{max}} - \sigma_{\text{min}}) \sqrt{\frac{\pi a}{Q}}$$
 (12)

$$R = \frac{\sigma_{\min}}{\sigma_{\max}} \tag{13}$$

where $\{\sigma_{max}, \sigma_{min}\}$ are respectively the maximum and minimum stresses of the constant amplitude load spectrum. Equation (10) will now be modified to describe the half-cycle crack growth.

The Half-Cycle Crack Growth Equation

In applying the half-cycle theory to calculate the crack growth induced by the random loading spectrum, it is assumed that the incremental amount of crack growth caused by each half-cycle with a particular load amplitude may be considered as a half-cycle of the constant amplitude loading spectrum with the same load amplitude. Therefore, the Walker crack growth equation, (10), may be used to calculate the incremental crack growth induced by each half-cycle of different load amplitude.

If the crack growth increment, da in equation (10), is set equal to the crack growth increment, δa_i , induced by the *i*-th (i = 1, 2, 3, ...) half cycle (i.e., $da = \delta a_i$), and the corresponding number of stress cycle increment, dN, is set equal to one half cycle (i.e., dN = 1/2), then the Walker crackgrowth equation (10) becomes the half-cycle crack growth equation for the calculations of half-cycle crack growth increment, δa_i . This half-cycle crack growth is expressed in equation (14).

$$\delta a_i = \frac{C}{2} \left[(K_{max})_i \right]^m (1 - R_i)^n = \frac{C}{2} (\Delta K_i)^m (1 - R_i)^{n - m}$$
(14)

where $\{(K_{\max})_i, \Delta K_i, R_i\}$ are respectively the values of $\{K_{\max}, \Delta K, R\}$ [See equations (11)–(13)] associated with the *i*-th half-cycle given by equations (15), (16), and (17).

$$(K_{\text{max}})_i = AM_k(\sigma_{\text{max}})_i \sqrt{\frac{\pi a_{i-1}}{Q}}$$
 ; $a_{1-1} = a_0 = a_c^p$ when $i=1$ (15)

$$\Delta K_i = AM_k \left[(\sigma_{\text{max}})_i - (\sigma_{\text{min}})_i \right] \sqrt{\frac{\pi a_{i-1}}{Q}}$$
(16)

$$R_i = \frac{(\sigma_{\min})_i}{(\sigma_{\max})_i} \tag{17}$$

where the subscript i (= 1, 2, 3,) is associated with the i-th half-cycle, and a_{i-1} is the cumulated crack size up to the (i-1)-th half-cycle. When i=1, the crack size a_{i-1} becomes $a_{i-1}=a_{1-1}=a_0=a_c^p$.

If N is any number of load cycles less than the total load cycles, N_1 , induced by the first flight, then the amount of the partial crack growth, Δa , induced by the N load cycles may be obtained from the crack growth equation (18) by summing up all the previous half-cycle crack growth increments, δa_i , up to 2N (not N) cycles as

$$\Delta a = \sum_{i=1}^{2N} \delta a_i \quad ; \quad (N \le N_1)$$
 (18)

The summation process of the half-cycle crack growth according to equation (18) is graphically illustrated in fig. 4 (refs. 2–4). Equation (18) is used to calculate the increasing partial crack growths, Δa , with increasing numbers of cycles, N, (or flight time steps) for generating the data set for plotting the crack growth curve (crack growth as a function of flight time) for the critical structural component. When N reached the total number of cycles, N_1 , ($N = N_1$), equation (19) will give the total amount of crack growth, Δa_1 , induced by the first flight. Namely,

$$(\Delta a)_{N=N_1} = \Delta a_1 = \sum_{i=1}^{2N_1} \delta a_i$$
 (19)

The value of Δa_1 , calculated from equation (19) is to be used as input to equation (9) for the calculation of the number of operational flights F_1^* of the failure-critical structural component.

CRACK GROWTH COMPUTER PROGRAM

To carry out the summation of the half-cycle crack growth increment, δa_i , on the right-hand side of equation (18) or (19), a special crack growth computer program was written. (see Appendix B for details). To use this program and its results, it is necessary to perform the following steps.

1) Create a new data file containing only the required data from the time taxiing begins to the time of test vehicle drop (or the time of complete stop after captive touchdown)

- because a flight-test load data file is normally very big covering the ground-sitting portion. Keep in mind that the flight data is the load spectrum and not the stress cycles at the critical stress point.
- 2) Use a spike remove program to remove noises (spikes) from a flight load spectrum since spikes can add in erroneously big crack growth.
- 3) Run the crack growth program. This program prompts for an unc3 format input filename. Then, it prompts for some important InterRange Instrumentation Group B (IRIGB) times in milliseconds of start taxiing, takeoff run, cruise power, and drop (or captive stop). After getting all required input data, the crack growth computer program performs the following key functions.
 - a. Read the input flight load spectrum. For each channel (associated with each hook) in the input file, the program picks up the maximum and minimum loads for the *i*-th half-cycle, $\{(V_{\text{max}})_i, (V_{\text{min}})_i\}$. The half-cycle maximum load, $(V_{\text{max}})_i$, is determined when the load is bigger than the two adjacent loads; and conversely, the minimum load, $(V_{\text{min}})_i$, of the same half-cycle is determined when load is smaller than the two adjacent loads.
 - b. The loads $\{(V_{\text{max}})_i, (V_{\text{min}})_i\}$ and their corresponding IRIGB times are saved in asc2 format output files. The names for the asc2 files are simple. For channel vap, the filename is sigma_vap.asc2.
 - c. The loads $\{(V_{\max})_i, (V_{\min})_i\}$ are then converted into the corresponding maximum and minimum stresses, $\{(\sigma_{\max})_i, (\sigma_{\min})_i\}$, of the *i*-th half cycle using equation (1).
 - d. Calculate the half-cycle crack growth increment, δa_i , using equation (14), and summing up δa_i over different numbers of load cycles, N (or a time step), to generate a data set of different partial crack growths, Δa , from equation (18).
 - e. Compute the total crack growth, Δa_1 , from equation (19) for the entire flight (from the time of start taxiing to the time of drop or captive stop) for approximately every minute. The times in minutes (zero at start taxiing time) and its corresponding Δa_1 are saved in an unc3 output file.
 - f. Determine the worst half-cycle from the loading spectrum during takeoff run and cruise power using the criterion of equation (3) and obtain the operational maximum load, V_{\max}^o , of the worst half-cycle.
 - g. Compute the load factor, *f*, from equation (2).
 - h. Calculate the number of operational flights, F_1^* from equation (9) based on the first flight load data.

- i. Generate a summary report in text format. This file contains the name of each B-52B hook in the input file, its total crack growth for the first flight, Δa_1 , its number of operational flights, F_1^* , its operational load factor f, its worst half cycle maximum load V_{\max}^o , its worst half-cycle minimum load, V_{\min}^o , and the corresponding IRIGB time. It also has the values of the numerator and the denominator that are used to calculate F_1^* .
- j. Print on screen the names of the crack growth output file and the summary file.
- 4) Convert the crack growth file to asc2 format and then to Mircosoft (Redmond, Washington) Excel format.
- 5) Graphically plot Δa as a function of flight time in minutes using Excel.

OPERATIONAL LIFE ANALYSIS

The Ko aging theory with the half-cycle crack growth theory incorporated, will now be applied to calculate the operational life spans of the three B-52B pylon hooks, and the four Pegasus adapter pylon hooks carrying the HXLV.

Two types of flights were analyzed: 1) air-launching flight, 2) captive flight. The air-launching flight lasted for 106 minutes, counted from the time of B-52B break release for taxiing until the time of air launching (dropping of the HXLV). The captive flight (no air-launching of the HXLV) lasted for 191 minutes, counted from the time of B-52B break release for taxiing and takeoff until the time of complete stop after captive landing.

The purpose of the analysis is to compare the crack growths, Δa_1 , induced by the first air-launching and first captive flight, and find out how many air-launching flights will be consumed by each captive flight. The actual flight loading data were used for the operational life calculations.

The B-52B and Pegasus Pylon Hooks

Figures 5–10, taken from reference 8, respectively show the geometry of B-52B pylon hooks (figs. 5, 7), and a typical Pegasus adapter pylon hook (fig. 9). The tangential tensile stress distribution over the inner boundary of each hook, obtained from finite-element stress analysis (figs. 6, 8, 10), is also shown, together with the locations of the critical stress points and the stress/load relationships indicated. The stress/load coefficients, η , for B-52B pylon hooks and Pegasus adapter pylon hooks established from the finite-element stress analysis are summarized in table 2 (taken from ref. 8).

Table 2. Proof loads, V^* , and stress/load coefficients, η , for B-52B pylon hooks and Pegasus adapter pylon hooks.

Hooks	V^* , lb	η , ksi/lb
VA	36,500	7.3522×10 ⁻³
VBL	57,819	5.8442×10 ⁻³
VBR	57,819	5.8442×10 ⁻³
VPFL	75,000	2.4459×10 ⁻³
VPFR	75,000	2.4459×10 ⁻³
VPRL	75,000	2.4459×10 ⁻³
VPRR	75,000	2.4459×10^{-3}

The stress/load coefficients, η , listed in table 2 are to be input to the crack-growth computer program to convert the loading spectrum of each hook into the stress cycles associated with the critical stress point using equation (1).

Flight Load Spectra

Figures 11–17 respectively show the flight load spectra of the B-52B pylon hooks and the Pegasus adapter pylon hooks carrying the HXLV during the takeoff run of the first air-launching flight. The location of the worst half-cycle and the value of the load factor, f, are indicated in each figure. The worst half-cycle was located by means of the crack growth computer program searching over the takeoff run portion of each flight load spectrum, and then finding the value of the operational maximum load, $V_{\rm max}^o$ (= $\sigma_{\rm max}^o/\eta$), of the worst half-cycle with minimum load ratio or stress ratio, R^o expressed in equation (20),

$$R^{o} = \frac{\sigma_{\min}^{o}}{\sigma_{\max}^{o}} = \frac{\eta V_{\min}^{o}}{\eta V_{\max}^{o}} = \frac{V_{\min}^{o}}{V_{\max}^{o}} = \text{ minimum}$$
 (20)

The value of V_{max}^o (or σ_{max}^o) was then used to calculate the load factor, f, for each hook using equation (2).

Crack Growth Calculations

The material properties of B-52B pylon hooks and Pegasus adapter pylon hooks listed in Appendix C were used for the crack growth calculations. In the present crack growth calculations, the surface crack (A = 1.12) at the critical stress point of each hook was assumed to be a very shallow ($M_k = 1$) semi-elliptic surface crack. Only one aspect ratio, a/2c = 1/4 (Q = 1.2548, table

1) was considered. As mentioned earlier, the value a/2c = 1/4 is the aspect ratio of the microsurface crack which caused the failure of a B-52B pylon old rear left hook (ref. 7). The crack-growth computer program was then used to read the values of $\{(V_{\text{max}})_i, (V_{\text{min}})_i\}$ for each half-cycle over the loading spectrum, and converted them into the corresponding stresses $\{(\sigma_{\text{max}})_i, (\sigma_{\text{min}})_i\}$ through equation (1) using the η values given in table 2 to calculate the half-cycle crack growth increment, δa_i , using equation (14). Finally, δa_i are summed up to different desired cycles (or time steps) to obtain partial crack growth, Δa , using equation (18) for generating a data set for plotting the crack growth curve for each hook. This process is graphically illustrated in fig. 3 and 4.

Number of Operational Flights

After the total crack growth, Δa_1 , induced by the first flight is calculated from equation (19) with the aid of the crack-growth computer program, the operational life equation (9) was then used to calculate the safe number of operational flights, F_1^* , allowed for the B-52B pylon hooks and Pegasus adapter pylon hooks to carry the HXLV for air-launching and captive flights.

RESULTS

The following sections discuss the results of the operational life analysis of the B-52B pylon hooks and the Pegasus adapter pylon hooks carrying the HXLV. This analysis uses the Ko aging theory and is aided by the half-cycle crack growth calculation method.

Crack Growth Curves

The crack growth curve is a very powerful tool for visually observing the crack growth behavior at the critical stress point of each failure-critical component. The crack growth curve for each hook was generated for the following two types of flights: air-launching flight and captive flight.

Air-Launching Flight

Figures 18–20 respectively show the crack growth curves generated for the three B-52B pylon hooks. Those crack growth curves were calculated from equation (18) with the crack growth summation carried out by the crack-growth computer program using the first air-launching flight data. Notice that the crack growth rate for each hook is quite rapid during taxiing because of ground effect, and became more accelerated (illustrated by a steeper slope on the graph) during the takeoff run as the ground-induced vibrations intensified. Once airborne, the ground effect diminished and, therefore, the crack growth rate slowed down considerably and stayed relatively constant (except for encountering wind gusts) until air-launching. The crack growth curve for the B-52B front hook (VA, fig. 18) exhibits the steepest takeoff-run slope as compared with the B-52B two rear hooks (VBL and VBR, figs. 19, 20). The rapid crack growth of the B-52B front hook during the takeoff run could be attributed in part to the overhanging effect of the X-43, which is at a forward distance from the front hook. For the three B-52B pylon hooks, (VA, VBL, VBR), taxiing and takeoff runs

combined induced approximately 65, 51, and 41 percent of the respective total crack growth, Δa_1 , per flight.

Figures 21–24 respectively show the crack growth curves for the four Pegasus adapter pylon hooks (VPFL, VPFR, VPRL, and VPRR). Those crack growth curves were generated from the crack growth computer program in carrying out the summation in equation (18) using the first air-launching-flight load data. The crack growth behavior of the Pegasus adapter pylon hooks is similar to that of the B-52B hooks, but with lower crack growth rates, especially during cruise flight. For the four Pegasus adapter pylon hooks (VPFL, VPFR, VPRL, and VPRR), the taxiing and takeoff run combined induced approximately 45, 60, 64, and 41 precent of the respective total crack growth, Δa_1 , per flight.

Captive Flight

Figures 25–27 respectively show the crack growth curves generated for the three B-52B pylon hooks (VA, VBL, and VBR) using the first captive-flight data. These crack growth curves were calculated from equation (18) with the crack growth summation carried out by the crack-growth computer program. Notice that, for each B-52B pylon hook, the amounts of crack growth and the crack growth rates (shown by slopes on the graphs) during the takeoff phase and the landing phase are quite similar. During the smooth cruise phase, the B-52B airplane encountered only two minor wind gusts (gust 1 and gust 2). The cruising crack growth rate of the front hook (VA, fig. 25) is much slower than those of the two rear hooks (VBL and VBR, figs. 26, 27). At the end of the cruise, three gusts were encountered by the B-52B airplane. The most severe, gust 5 coinciding with the B-52B maneuver, caused the crack growth rate for each hook to increase rapidly (portrayed by steeper slopes). For these three hooks, the fastest crack growth rates occurred during both the takeoff phase and landing phase because of severe ground effects. For the three B-52 hooks (VA, VBL, VBR), the takeoff phase and the landing phase combined contributed approximately 67, 54, and 51 percent of the respective total crack growth, Δa_1 , per flight. The crack growth rate of the outboard right rear hook (VBR) during cruising flight is slightly faster than that of the inboard left rear hook (VBL). This phenomenon was also observed in the air-launching flight-test case (figs. 19, 20).

Figures 28–31 respectively show the crack growth curves generated for the Pegasus adapter pylon hooks (VPFL, VPFR, VPRL, and VPRR) by the crack growth computer program. The program carried out the summation of half-cycle crack growths, calculated by equation (18), associated with the first captive-flight load spectra. The crack growth curves of the Pegasus adapter pylon hooks are similar to those of the B-52B hooks, but with lower crack growth rates, especially during cruise flight. For the four Pegasus adapter pylon hooks (VPFL, VPFR, VPRL, and VPRR), the takeoff phase and landing phase combined induced nearly 51, 59, 71, and 51 percent of the respective total crack growth, Δa_1 , per flight.

Number of Operational Flights

The number of possible operational flights for each of the B-52B pylon hooks and of Pegasus adapter pylon hooks (carrying the HXLV) were calculated from the operational life equation, (9). Flight test data was obtained from two types of test flights, air-launching and captive.

Air-Launching Flight

For the air-launching flight, which lasted for 106 minutes, the key input and output data generated for different hooks are listed in table 3 for crack geometry a/2c = 0.25 (Q = 1.2548).

Table 3. Key data for the B-52B airplane carrying the Hyper-X launch vehicle (total weight: 40,000 lb); 106-min air-launching flight; a / 2c = 0.25 (Q = 1.2548).

Hooks	V^* , lb	V_{\max}^o , lb	f	a_c^p , in	Δa_1 , in	F_1^* , flights
VA	36,500	18,065	0.4949	0.0691	1.9258×10 ⁻⁴	304
VBL	57,819	23,227	0.4017	0.0429	2.5367×10 ⁻⁴	186^{\dagger}
VBR	57,819	18,906	0.3270	0.0429	2.5734×10 ⁻⁴	203
VPFL	75,000	34,367	0.4582	0.1455	1.6680×10 ⁻⁴	873
VPFR	75,000	34,623	0.4616	0.1455	1.8326×10^{-4}	790
VPRL	75,000	21,179	0.2824	0.1455	1.4053×10^{-4}	$1,323^{\dagger\dagger}$
VPRR	75,000	21,413	0.2855	0.1455	1.5441×10^{-4}	1,200

[†] Shortest operational life, †† Longest operational life

Table 3 shows that, among the three B-52B pylon hooks, the rear left hook (VBL) has the shortest life (186 flights), and the front hook (VA) has the longest life (304 flights). Although the crack growths for VBL and VBR are quite close, the higher value of f for VBL (f = 0.4017) caused the operational life of VBL to be shorter than VBR (f = 0.3270).

Among the four Pegasus pylon adapter hooks, the front right hook (VPFR) has the shortest life (790 flights), and the rear left hook (VPRL) has the longest life (1323 flights).

Captive Flight

For the captive flight which had a duration of 191 minutes, the resulting key input and output data for different hooks are listed in table 4 for a/2c = 0.25 (Q = 1.2548).

Table 4. Key data for the B-52B airplane carrying the Hyper-X launch vehicle)
(total weight: 40,000 lb); 191-min captive flight; $a / 2c = 0.25$ ($Q = 1.2548$).	

Hooks	V^* , lb	V_{\max}^o , lb	f	a_c^p , in	Δa_1 , in	F_1^* , flights
VA	36,500	17,171	0.4704	0.0691	6.7226×10 ⁻⁴	91
VBL	57,819	21,616	0.3739	0.0429	7.4446×10^{-4}	83^{\dagger}
VBR	57,819	17,875	0.3092	0.0429	5.8556×10 ⁻⁴	92
VPFL	75,000	33,482	0.4464	0.1455	2.1151×10 ⁻⁴	477
VPFR	75,000	34,137	0.4552	0.1455	3.3859×10^{-4}	433
VPRL	75,000	22,565	0.3009	0.1455	3.1070×10 ⁻⁴	586 ^{††}
VPRR	75,000	21,087	0.2812	0.1455	3.3090×10 ⁻⁴	563

[†] Shortest operational life, †† Longest operational life

Table 4 shows that, like the air-launching flight, the life of the B-52B pylon rear left hook (VBL) at 83 flights is shorter than the identical rear right hook (VBR) at 92 flights because of higher values of $\{\Delta a_1, f\}$. Among the four identical Pegasus pylon hooks, the front right hook has the shortest life (433 flights), and the rear left hook (VPRL) has the longest life (586 flights). Also, note from table 4 that crack growths, Δa_1 , induced by the captive flight are approximately 2–3 times larger than Δa_1 induced by the air-launching flight, therefore, the flight life of each hook is reduced.

Table 5 compares the operational flight life of each hook undergoing air-launching flight and captive flight. The ratio $\frac{(F_1^*)_{\text{Air-launching}}}{(F_1^*)_{\text{Captive}}}$ will then give the number of air-launching flights consumed by each captive flight.

Table 5. Summary of available number of flights: B-52B carrying Hyper-X launch vehicle (total weight: 40,000 lb); 106-min air-launching flight; 191 min captive flight.

** 1	F_1^* , flig	ghts	Number of air-launching flights consumed by each captive flight
Hook	Air-launching (A)	Captive (C)	(A) (C)
VA	304	91	3.34 (≈ 3)
VBL	186^{\dagger}	83†	2.24 (≈ 2)
VBR	203	92	2.21 (≈ 2)
VPFL	873	477	1.83 (≈ 2)
VPFR	790	433	1.82 (≈ 2)
VPRL	$1,323^{\dagger\dagger}$	586 ^{††}	2.26 (≈ 2)
VPRR	1,200	563	2.13 (≈ 2)

[†] Shortest operational life, †† Longest operational life

Note from table 5 that each captive flight consumed 2–3 air-launching flights (depending on the type of hooks) because it had a longer flight duration, encountered more air gusts, experienced aircraft maneuvers, and had a landing phase.

CONCLUSIONS

The half-cycle crack growth theory was incorporated into the Ko closed-form aging theory for accurate crack growth calculations, which would thereby improve the accuracy of predictions of operational life of failure-critical aerostructural components. The unified theories were then used to calculate the number of operational flights permitted for B-52B pylon hooks and Pegasus adapter pylon hooks carrying the HXLV. The highlights of the operational life analysis are:

- 1) A new crack growth computer program was written to remove the noises, to read the maximum and minimum loads of each half-cycle of the random-flight loading spectra, and then to calculate the crack growths based on the half-cycle crack growth theory.
- 2) The crack growths calculated from the half-cycle crack growth program should be quite accurate because every half-cycle of each random loading spectrum was counted, including those secondary mini-amplitude half-cycles which did not even cross over the mean stress lines.
- 3) The crack growth curve generated for each hook using the newly written crack growth computer program is a powerful practical tool for visualization of crack growth behavior at the critical point of each hook during all phases of flight.
- 4) The crack growth rates are most rapid during the takeoff phase (brake release for taxiing

- and takeoff run) and landing phase (touchdown and taxiing to stop) because of ground effect, and induced a large percentage of the total crack growth per flight.
- 5) Once airborne and during cruise, the crack growth rate decreased significantly, and stayed almost constant, except for encountering wind gusts and aircraft maneuvers.
- 6) For air-launching flight (the B-52B airplane carrying and launching the HXLV), taxiing and takeoff combined induced approximately 41–65 precent of the total crack growth per flight depending on the types of hooks. The B-52B pylon rear left hook (VBL) has the shortest operational life of 186 flights, and the Pegasus pylon adapter rear left hook (VPRL) has the longest operational life of 1323 flights.
- 7) For captive flight (the B-52B airplane carrying the HXLV), the takeoff phase and the landing phase combined induced approximately 51–71 percent of the total crack growth per flight depending on the types of hooks. The B-52B pylon rear left hook (VBL) has the shortest operational life of 83 flights, and the Pegasus pylon adapter rear left hook (VPRL) has the longest operational life of 586 flights.
- 8) Each captive flight is equivalent to 2–3 air-launching flights (depending on the type of hooks) because of longer flight time, encountering more wind gusts, intended aircraft maneuvers, and an additional captive landing phase.

Dryden Flight Research Center National Aeronautics and Space Administration Edwards, California, October 12, 2006

APPENDIX A OPERATIONAL LIFE EQUATIONS

The original Ko closed-form operational life equation (refs. 5, 6) has the mathematical form given by equation (A1)

$$F_1^* = \frac{(a_c^p)^{1-\frac{m}{2}} - (a_c^o)^{1-\frac{m}{2}}}{(a_c^p)^{1-\frac{m}{2}} - (a_1)^{1-\frac{m}{2}}} = \frac{1 - \left(\frac{a_c^o}{a_c^p}\right)^{1-\frac{m}{2}}}{1 - \left(\frac{a_1}{a_c^p}\right)^{1-\frac{m}{2}}}$$
(A1)

From equation (5), the crack-ratio/load-factor relationship is established as seen in equation (A2).

$$\frac{a_c^o}{a_c^p} = \frac{1}{f^2} \tag{A2}$$

As seen in equation (A3) the crack size at the end of the first flight, a_1 , may be expressed in terms of the crack growth, Δa_1 , for the first flight as

$$a_1 = a_c^p + \Delta a_1 \tag{A3}$$

In light of equations (A2) and (A3), equation (A1) may be written in more compact form in terms of f in equation (A4)

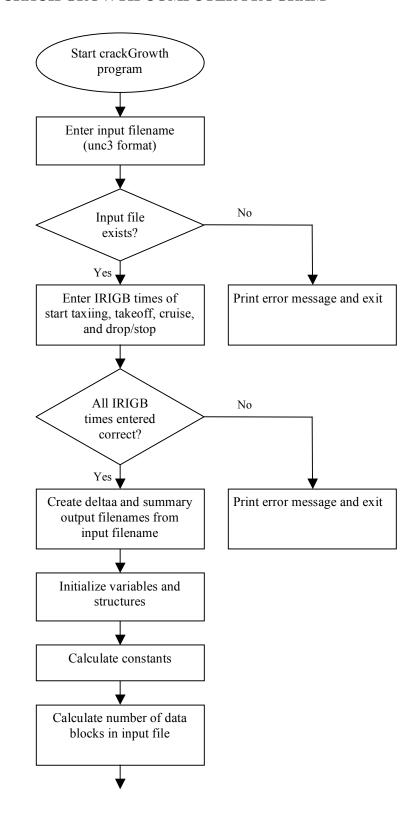
$$F_{1}^{*} = \frac{1 - \left(\frac{1}{f^{2}}\right)^{1 - \frac{m}{2}}}{1 - \left(\frac{a_{c}^{p} + \Delta a_{1}}{a_{c}^{p}}\right)^{1 - \frac{m}{2}}} = \frac{1 - \left(\frac{1}{f}\right)^{2 - m}}{1 - \left(1 + \frac{\Delta a_{1}}{a_{c}^{p}}\right)^{1 - \frac{m}{2}}}$$
(A4)

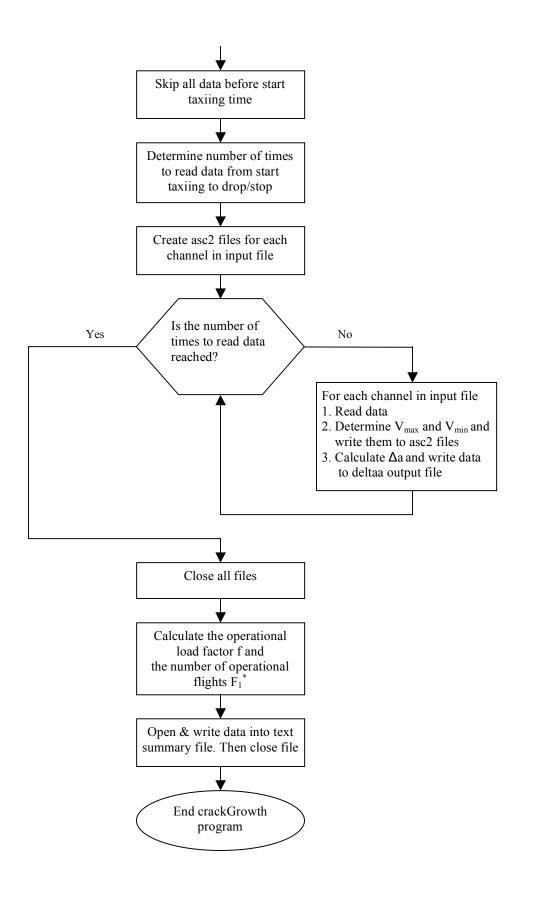
which may be rewritten in equation (A5) as

$$F_1^* = \frac{1 - f^{m-2}}{1 - \left(1 + \frac{\Delta a_1}{a_c^p}\right)^{1 - \frac{m}{2}}}$$
(A5)

which is equation (9), the Ko operational life equation, in the text.

APPENDIX B CRACK GROWTH COMPUTER PROGRAM





/*************************

- * Tittle: crackGrowth.c -- Crack Growth Program
- * Written by: Van T. Tran
- * Organization: Aerostructures Branch, RS, NASA Dryden Flight Research Center
- * Date: August 3, 2004

* Introduction:

- This program is written in C programming language. It only works with flight test data files that have unc3 format. First, it prompts for an input filename. Then, it prompts for some important InterRange Instrumentation Group B (IRIGB) times in milliseconds.
- These IRIG times consist of start taxiing, takeoff run, cruise power, and drop/stop. After
- getting all entered inputs, it performs several tasks for each channel in the input file such
 - as calculating the accumulated crack growth size, the number of operational flights,
- the operational load factor, creating output files, and generating a summary report.
- When it finishes, it prints on the screen the unc3 format output filename and the text summary filename.

* *

There are different data formats at Dryden Flight Research Center. The text formats consist of asc1 (ASCII 1) and asc2 (ASCII 2). The binary formats include unc2 (uncompressed 2), unc3 (uncompressed 3), cmp3 (compressed 3), and cmp4 (compressed 4). To convert a file from one format to another format, use getdata and/or getdata3 programs.

An unc3 format input file contains loading spectra.

* Outputs:

1. unc3 output filename = input filename deltaa.unc3. This file contains IRIGB times and the corresponding crack growths, Δa , for all channels in the input file. Δa is calculated using the half-cycle crack growth theory.

- 2. txt output filename = input filename summary.txt. This file contains the following information for all channels in the input file:
 - Δa_1 , the final sum of crack growths
 - F_1^* , the number of operational flights, calculated by using Ko operational life equation.

*

* *

- f, the operational load factor.
- the worst half-cycle $V_{\rm max}^0$, $V_{\rm min}^0$, and the corresponding IRIGB time.
- the numerator and the denominator used in calculation of F_1^* .

*

3. asc2 output filename = sigma channel name.asc2. Each sigma file contains IRIGB

```
time, half-cycle V_{\rm max} and V_{\rm min} for each channel in the input file.
*
* Procedure to use crackGrowth program:
    1. Use getdata3 to convert flight test data file to asc2 format.
*
    2. Use vi, xemacs or textedit editor to filter the data so that the input file contains only
      data from start taxiing time to drop/stop time.
*
    3. Use getdata3 to convert the filtered data file to unc3 format input file.
    4. Use any spike remove program to remove spikes in the input file.
    5. Run crackGrowth program by type in crackGrowth at the command line.
    6. Enter all required data as prompted on screen.
    7. Program crackGrowth is done when complete message is displayed on screen.
    8. Use getdata3 program to convert output file xxxx deltaa.unc3 to asc2 format.
   9. Convert asc2 format to excel format
  10. Use Excel to plot the data
   11. Use vi, xemacs or textedit editor to read xxxx summary.txt file.
   12. Use vi, xemacs or textedit editor to read sigma xxxx.asc2 files.
* Initial Release: November 2004
*****************************
/* Header Files */
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <fcntl.h>
#include <unistd.h>
#include <sys/stat.h>
#include <svs/ddi.h>
#include <math.h>
/* Library subroutines */
double
          sqrt(double x);
          pow(double x, double y);
double
/* Define constants */
#define
          FALSE
                                          0
#define
          TRUE
                                          1
#define
          ERROR
                                          -1
#define
          NAMES SIZE
                                          16
          TITLE LENGTH
#define
                                          80
#define
          FNAME LENGTH
                                          200
```

#define #define #define	NUM_BYTES MAXCHANS MAXBUFS	4 30 5000
#define #define	MAXSIZE NUM_SECONDS	512 60
#define	NONE	0
#define	MIN	1
#define	MAX	2
#define	EQUAL	3
#define	A	1.12
#define	Mk	1
#define	Q	1.2548
#define	PI	3.14159265359
#define	Eta FRONT HOOK	0.0073522
#define	Eta_REAR_HOOK	0.0058442
#define	Eta_PEGASUS	0.0024459
#define	Vstar FRONT HOOK	36500.0
#define	Vstar_REAR_HOOK	57819.0
#define	Vstar_PEGASUS	75000.0
#define	Kic FRONT HOOK	125.0
#define	Kic_REAR_HOOK	124.0
#define	Kic_PEGASUS	124.0
#define	C_FRONT_HOOK	0.000000000000922
#define	C_REAR_HOOK	0.00000000002944
#define	C_PEGASUS	0.00000000002944
#define	m FRONT HOOK	3.6
#define	m_REAR_HOOK	3.24
#define	m_PEGASUS	3.24
#define	n FRONT HOOK	2.16
#define	n_REAR_HOOK	1.69
#define	n_PEGASUS	1.69
#define	f VA	0.4656
#define	f_VBL	0.3720
#define	f_VBR	0.3328
#define	f_VPFL	0.4585
#define	f_VPFR	0.4747
#define	f_VPRL	0.2607

```
#define
                                        0.2966
           f VPRR
/* Define structure */
struct buffer_struct
  unsigned long irig_time;
                                        /* IRIG B time
  float euc data[MAXCHANS];
                                        /* EUC data
};
/* getdata format record format */
struct
  short
              size;
  char
              text[8];
  char
              type[8];
  char
              ver[8];
format = {sizeof(format), "format ", "unc 3 ", ".1
                                                     "};
/* getdata nChans record format */
struct
  short
              size;
  char
              text[8];
  short
              dummy;
  short
              count;
nchans = {sizeof(nchans), "nChans ", 0, 0};
/* getdata timekey record format */
struct
  short
              size;
  char
              text[8];
  short
              dummy;
  short
              count;
timekey = {sizeof(timekey), "timekey ", 0, 1000};
/* getdata title record format */
struct
```

```
short
            size;
  char
            text[8];
  char
            titl[TITLE LENGTH];
title = {sizeof(title), "title "};
/* getdata names record format */
struct
  short
            size;
  char
            text[8];
names = \{0, \text{"names "}\};
/* getdata endhead record format */
struct
  short
            size;
            text[8];
  char
endhead = {sizeof(endhead), "endHead "};
/* Define variables */
char
       input file[FNAME LENGTH];
char
       output file1[FNAME LENGTH];
char
       output file2[FNAME LENGTH];
       f vap[FNAME LENGTH];
char
char
       f vas[FNAME LENGTH];
char
       f vbrp[FNAME LENGTH];
       f vbrs[FNAME LENGTH];
char
char
       f vblp[FNAME LENGTH];
char
       f vbls[FNAME LENGTH];
char
       f vprrp[FNAME LENGTH];
char
       f vprrs[FNAME LENGTH];
char
       f vprlp[FNAME LENGTH];
       f vprls[FNAME LENGTH];
char
char
       f vpfrp[FNAME LENGTH];
char
       f vpfrs[FNAME LENGTH];
       f vpflp[FNAME LENGTH];
char
       f vpfls[FNAME LENGTH];
char
```

```
char
       sigma txt[MAXCHANS][FNAME LENGTH];
char
       chan name[MAXCHANS][NAMES SIZE];
char
       asc2 name[MAXCHANS][26];
FILE
       *fpin;
       *fpout1;
FILE
FILE
       *fpout2:
FILE
       *fp sigma txt[MAXCHANS];
struct
       buffer struct data buffer;
struct
       buffer struct data write1;
struct
       buffer struct data write2;
struct
       buffer struct data read[MAXBUFS];
double
       C OVER 2[MAXCHANS];
       deltaa[MAXCHANS][MAXBUFS], sum a[MAXCHANS],
double
        sum deltaa[MAXCHANS];
double
       apc[MAXCHANS], apc FRONT HOOK, apc REAR HOOK, apc PEGASUS;
float
       buff endfile[MAXSIZE];
float
       calc euc[MAXBUFS], temp_euc[MAXBUFS];
       stress coef[MAXCHANS], Kic[MAXCHANS], m[MAXCHANS], n[MAXCHANS];
float
float
       Vstar[MAXCHANS], prev_value[MAXCHANS], end_value[MAXCHANS];
float
       min max value[MAXCHANS][MAXBUFS], last data[MAXCHANS];
float
       f[MAXCHANS], Vmax[MAXCHANS], Vmin[MAXCHANS], Ri min[MAXCHANS];
float
       numerator[MAXCHANS], denominator[MAXCHANS];
int
       num chans, names size;
int
       buf size, normal buf;
       max data read, int flight[MAXCHANS];
int
long
       unc3 endfile = -1;
short
       first time, last data read;
       prev_type[MAXCHANS], end_type[MAXCHANS], first_type[MAXCHANS];
short
short
       do calc[MAXCHANS], write index[MAXCHANS];
short
       last index[MAXCHANS];
short
       processed done[MAXCHANS];
unsigned long fp, fp eof, fp skip, fp read, data buff size, num data blocks;
unsigned long starting time entered starting time:
unsigned long drop time entered, drop time, dt;
unsigned long takeoff time entered, takeoff time;
unsigned long cruise time entered, cruise time;
unsigned long time deltaa:
unsigned long num blocks, num read;
```

```
unsigned long min max time[MAXCHANS][MAXBUFS], last data time[MAXBUFS],
               Tmax[MAXCHANS];
/* Subroutines used by the main program */
void get header info();
void write asc2 header();
void skip data();
void read data();
void determine max min();
void calculate deltaa();
void calculate flights();
void generate summary();
main(argc, argv)
int argc;
char *argv[];
          name[NAMES SIZE];
  char
          i, j, k, l;
  int
  double A sgre, Mk sgre, Q over PI, Kic sgre, load sgre;
 /* Screen display */
  printf("\ncrackGrowth program written by : Van T. Tran");
  printf("\nNASA/Dryden Flight Research Center, Code RS");
 printf("\nInitial Release - November 2004\n\n");
  /* Prompt user for the input filename */
  printf("crackGrowth: Enter input file name ");
 scanf("%s", input file);
 /* Check if input filename exists */
  if ((fpin = fopen(input file, "r")) == NULL)
   printf("\nError in openning input file %s\n\n", input file);
   printf("\ncrackGrowth program terminated\n\n");
   exit (1);
 /* Need start taxiing time in miliseconds */
  printf("\ncrackGrowth: Enter Irigb starting time in msec (integer) ");
```

```
scanf("%d", &starting time entered);
printf("Entered Irigb starting time is %d\n\n", starting time entered);
starting time = starting time entered * 10;
/* Need takeoff run time in miliseconds */
printf("crackGrowth: Enter Irigb takeoff time in msec (integer) ");
scanf("%d", &takeoff time entered);
printf("Entered Irigb takeoff time is %d\n\n", takeoff time entered);
takeoff time = takeoff time entered * 10;
/* Need cruise power time in miliseconds */
printf("crackGrowth: Enter Irigb cruise time in msec (integer) ");
scanf("%d", &cruise time entered);
printf("Entered Irigb cruise time is %d\n\n", cruise_time_entered);
cruise time = cruise time entered * 10;
/* Need drop or stop time in miliseconds */
printf("crackGrowth: Enter Irigb drop or stop time in msec (integer) ");
scanf("%d", &drop time entered);
printf("Entered Irigb drop time is %d\n\n", drop time entered);
drop time = drop time entered * 10;
printf("crackGrowth program is running ...Do not interrupt ...\n");
strcpy(output file1, input file);
strcpy(output file2, input file);
/* Check if the input file has the extension of .unc3 */
if (strstr(input file, ".unc3") != NULL)
 i = strlen(output file1) - 5;
 strcpy(&output_file1[j], "_deltaa.unc3");
 strcpy(&output file2[j], "_summary.txt");
else
 strcat(output file1, " deltaa.unc3");
 strcat(output_file2, "_summary.txt");
/* Write the output filename */
```

```
if ((fpout1 = fopen(output file1, "w")) == NULL)
 printf("\nError in creating output file %s!", output file1);
 printf("\ncrackGrowth program terminated\n\n");
 exit (2);
if ((fpout2 = fopen(output file2, "w")) == NULL)
 printf("\nError in creating output file %s!", output_file2);
 printf("\ncrackGrowth program terminated\n\n");
 exit (2);
/* Initialize variables and structures */
bzero((char *) (&apc), sizeof(apc));
bzero((char *) (&data read), sizeof(data read));
bzero((char *) (&data write1), sizeof(data write1));
bzero((char *) (&data write2), sizeof(data write2));
bzero((char *) (&buff endfile), sizeof(buff endfile));
bzero((char *) (&write index), sizeof(write index));
bzero((char *) (&stress coef), sizeof(stress coef));
bzero((char *) (&deltaa), sizeof(deltaa));
bzero((char *) (&sum a), sizeof(sum a));
bzero((char *) (&sum deltaa), sizeof(sum deltaa));
bzero((char *) (&do calc), sizeof(do calc));
bzero((char *) (&chan name), sizeof(chan name));
bzero((char *) (&asc2 name), sizeof(asc2 name));
bzero((char *) (&prev type), sizeof(prev type));
bzero((char *) (&Vmax), sizeof(Vmax));
bzero((char *) (&Vmin), sizeof(Vmin));
bzero((char *) (&numerator), sizeof(denominator));
num chans = 0;
num blocks = 0;
num read = 0;
first time = TRUE;
last data read = FALSE;
A sqre = (double) A*A:
Mk \text{ sqre} = (double) Mk*Mk;
Q over PI = (double) Q/PI;
Kic sgre = (double) Kic FRONT HOOK*Kic FRONT HOOK;
load sqre = (double) Eta FRONT HOOK*Eta FRONT HOOK*
```

```
Vstar FRONT HOOK*Vstar FRONT HOOK;
apc FRONT HOOK = Q over PI * Kic sqre / (A sqre * Mk sqre * load sqre);
Kic sqre = (double) Kic REAR HOOK*Kic REAR HOOK;
load sgre = (double) Eta REAR HOOK*Eta REAR HOOK*
                   Vstar REAR HOOK*Vstar REAR HOOK;
apc REAR HOOK = Q over PI * Kic sqre / (A sqre * Mk sqre * load sqre);
Kic sqre = (double) Kic PEGASUS*Kic PEGASUS;
load sqre = (double) Eta PEGASUS*Eta PEGASUS*
                   Vstar PEGASUS*Vstar PEGASUS;
apc PEGASUS = Q over PI * Kic_sqre / (A_sqre * Mk_sqre * load_sqre);
/* Move the file position indicator to the end of input file */
fseek(fpin, 0, SEEK END);
/* Get the pointer at the end of file */
fp eof = ftell(fpin);
fp eof -= NUM BYTES;
/* Move the file position indicator to the beginning of input file */
fseek(fpin, 0, SEEK SET);
fp = ftell(fpin);
/* Call get header info subroutine */
get header info();
/* Calculate the number of data blocks in the input file */
num data blocks = (fp eof - fp) / data buff size;
/* Skip all data before start taxiing time */
skip data();
/* Determine the number of times to read data */
\max data read = (num data blocks / normal buf) + 1;
/* Create an asc2 format file for each channel */
for (i = 0; i < num chans; i++)
```

```
if (do calc[i] == TRUE)
   if ((fp sigma txt[i] = fopen(sigma txt[i], "w")) == NULL)
    printf("\nError in creating text file %s!", fp sigma txt[i]);
    printf("\ncrackGrowth program terminated\n\n");
     exit (2);
/* Create asc2 header for each channel */
write_asc2_header();
/* Read data, determine max & min, and calculate crack growth */
for (i = 0; i < max data read; i++)
 if (last data read == FALSE)
   read data();
   determine max min();
   calculate deltaa();
/* Write end of file to the output file */
fwrite(&unc3 endfile, sizeof(long), 1, fpout1);
fwrite(&buff endfile, sizeof(float)*MAXSIZE, 1, fpout1);
/* Close all files */
fclose(fpout1);
fclose(fpin);
for (i = 0; i < num chans; i++)
  if (do calc[i] == TRUE)
   fclose(fp sigma txt[i]);
printf("\n");
```

```
/* Calculate the number of operational flights */
 calculate flights();
 /* Generate a summary text file */
 generate summary();
 /* Close the summary text file */
 fclose(fpout2);
 /* Print the end message */
 printf("\ncrackGrowth program completed successfully!\n");
 printf("Crack growths are in %s\n", output file1);
 printf("Summary is in %s\n\n", output file2);
/**********************************
* Subroutine get header info()
* Description:
   This subroutine reads the header information in the unc3 input file and write the header
    information to the unc3 output file. The unc3 output file contains calculated crack
    growths and times in minutes for all channels. For each channel, all important constants
    are calculated and an asc2 format output file is generated. The asc2 filename has
    sigma following by the channel name and extension asc2. For channel vap, the asc2
    filename is sigma vap.asc2.
******************************
void get header info()
 int
         i;
         str loc;
 short
 /* Read and write header information */
 fread(&format, sizeof(format), 1, fpin);
 fwrite(&format, sizeof(format), 1, fpout1);
 /* Read the number of input channels and figure out the data buffer size */
 fread(&nchans, sizeof(nchans), 1, fpin);
 fwrite(&nchans, sizeof(nchans), 1, fpout1);
```

```
num chans = nchans.count;
data buff size = num chans * sizeof(float) + NUM BYTES;
fread(&timekey, sizeof(timekey), 1, fpin);
fwrite(&timekey, sizeof(timekey), 1, fpout1);
fread(&title, sizeof(title), 1, fpin);
fwrite(&title, sizeof(title), 1, fpout1);
names_size = num_chans * NAMES SIZE + 10;
/* Read and write channel names */
fread(&names, names size, 1, fpin);
fwrite(&names, names size, 1, fpout1);
str loc = sizeof(names.text);
/* Calculate and determine constants and create sigma filenames */
for (i = 0; i < num chans; i++)
 strncpy(chan name[i], &names.text[str loc], NAMES SIZE);
 str loc += NAMES SIZE;
 if (strstr(chan name[i], "vap") != NULL)
  stress coef[i] = Eta FRONT HOOK;
  Vstar[i] = Vstar FRONT HOOK;
  Kic[i] = Kic FRONT HOOK;
  apc[i] = apc FRONT HOOK;
  C OVER 2[i] = C FRONT HOOK /2.0;
  m[i] = m FRONT HOOK;
  n[i] = n FRONT HOOK;
  f[i] = f VA;
  do calc[i] = TRUE;
  Ri min[i] = 1000;
  strcpy(sigma txt[i], "sigma vap.asc2");
 else if (strstr(chan name[i], "vas") != NULL)
  stress coef[i] = Eta FRONT HOOK;
  Vstar[i] = Vstar FRONT HOOK;
  Kic[i] = Kic FRONT HOOK;
  apc[i] = apc FRONT HOOK;
  C OVER 2[i] = C FRONT HOOK / 2.0;
  m[i] = m FRONT HOOK;
```

```
n[i] = n FRONT HOOK;
 f[i] = f VA;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma_txt[i], "sigma_vas.asc2");
else if (strstr(chan name[i], "vbrp") != NULL)
 stress coef[i] = Eta REAR HOOK;
 Vstar[i] = Vstar REAR HOOK;
 Kic[i] = Kic REAR HOOK;
 apc[i] = apc REAR HOOK;
 C OVER 2[i] = C REAR HOOK / 2.0;
 m[i] = m REAR HOOK;
 n[i] = n REAR HOOK;
 f[i] = f VBR;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma txt[i], "sigma vbrp.asc2");
else if (strstr(chan name[i], "vbrs") != NULL)
 stress coef[i] = Eta REAR HOOK;
 Vstar[i] = Vstar REAR HOOK;
 Kic[i] = Kic REAR HOOK;
 apc[i] = apc REAR HOOK;
 C OVER 2[i] = C REAR HOOK / 2.0;
 m[i] = m REAR HOOK;
 n[i] = n REAR HOOK;
 f[i] = f VBR;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma txt[i], "sigma vbrs.asc2");
else if (strstr(chan name[i], "vblp") != NULL)
 stress coef[i] = Eta REAR HOOK;
 Vstar[i] = Vstar REAR HOOK;
 Kic[i] = Kic REAR HOOK;
 apc[i] = apc REAR HOOK;
 C OVER 2[i] = C REAR HOOK / 2.0;
 m[i] = m REAR HOOK;
 n[i] = n REAR HOOK;
 f[i] = f VBL;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
```

```
strcpy(sigma txt[i], "sigma vblp.asc2");
else if (strstr(chan name[i], "vbls") != NULL)
stress coef[i] = Eta REAR HOOK;
 Vstar[i] = Vstar REAR HOOK;
Kic[i] = Kic REAR HOOK;
apc[i] = apc REAR HOOK;
 C OVER 2[i] = C REAR HOOK / 2.0;
m[i] = m REAR HOOK;
n[i] = n REAR HOOK;
f[i] = f VBL;
do calc[i] = TRUE;
Ri min[i] = 1000;
strcpy(sigma_txt[i], "sigma_vbls.asc2");
else if (strstr(chan name[i], "vprrp") != NULL)
stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
 Kic[i] = Kic PEGASUS;
apc[i] = apc PEGASUS;
 C OVER 2[i] = C PEGASUS / 2.0;
m[i] = m PEGASUS;
n[i] = n PEGASUS;
f[i] = f VPRR;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
strcpy(sigma txt[i], "sigma vprrp.asc2");
else if (strstr(chan name[i], "vprrs") != NULL)
stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
Kic[i] = Kic PEGASUS;
apc[i] = apc PEGASUS;
C OVER 2[i] = C PEGASUS / 2.0;
m[i] = m PEGASUS;
n[i] = n PEGASUS;
 f[i] = f VPRR;
do calc[i] = TRUE;
Ri min[i] = 1000;
strcpy(sigma txt[i], "sigma vprrs.asc2");
else if (strstr(chan name[i], "vprlp") != NULL)
```

```
stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
 Kic[i] = Kic PEGASUS;
 apc[i] = apc PEGASUS;
 C_OVER_2[i] = C_PEGASUS / 2.0;
 m[i] = m PEGASUS;
 n[i] = n PEGASUS;
 f[i] = f VPRL;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma txt[i], "sigma vprlp.asc2");
else if (strstr(chan name[i], "vprls") != NULL)
 stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
 Kic[i] = Kic PEGASUS;
 apc[i] = apc PEGASUS;
 C OVER 2[i] = C PEGASUS / 2.0;
 m[i] = m PEGASUS;
 n[i] = n PEGASUS;
 f[i] = f VPRL;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma txt[i], "sigma vprls.asc2");
else if (strstr(chan name[i], "vpfrp") != NULL)
 stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
 Kic[i] = Kic PEGASUS;
 apc[i] = apc PEGASUS;
 C OVER 2[i] = C PEGASUS / 2.0;
 m[i] = m PEGASUS;
 n[i] = n PEGASUS;
 f[i] = f VPFR;
 do calc[i] = TRUE;
 Ri min[i] = 1000;
 strcpy(sigma txt[i], "sigma vpfrp.asc2");
else if (strstr(chan name[i], "vpfrs") != NULL)
 stress coef[i] = Eta PEGASUS;
 Vstar[i] = Vstar PEGASUS;
 Kic[i] = Kic PEGASUS;
 apc[i] = apc_PEGASUS;
```

```
C OVER 2[i] = C PEGASUS / 2.0;
  m[i] = m PEGASUS;
  n[i] = n PEGASUS;
  f[i] = f VPFR;
   do calc[i] = TRUE;
  Ri min[i] = 1000;
  strcpy(sigma_txt[i], "sigma_vpfrs.asc2");
  else if (strstr(chan name[i], "vpflp") != NULL)
  stress coef[i] = Eta PEGASUS;
   Vstar[i] = Vstar PEGASUS;
   Kic[i] = Kic PEGASUS;
   apc[i] = apc PEGASUS;
  C_OVER_2[i] = C_PEGASUS / 2.0;
  m[i] = m PEGASUS;
  n[i] = n PEGASUS;
   f[i] = f VPFL;
   do calc[i] = TRUE;
   Ri min[i] = 1000;
  strcpy(sigma txt[i], "sigma vpflp.asc2");
  else if (strstr(chan name[i], "vpfls") != NULL)
  stress coef[i] = Eta PEGASUS;
   Vstar[i] = Vstar PEGASUS;
  Kic[i] = Kic PEGASUS;
  apc[i] = apc_PEGASUS;
  C OVER 2[i] = C PEGASUS / 2.0;
  m[i] = m PEGASUS;
  n[i] = n PEGASUS;
   f[i] = f VPFL;
  do calc[i] = TRUE;
  Ri min[i] = 1000;
  strepy(sigma txt[i], "sigma vpfls.asc2");
 else
  do calc[i] = FALSE;
/* Read the end header of the input file and write it to the output file */
fread(&endhead, sizeof(endhead), 1, fpin);
fwrite(&endhead, sizeof(endhead), 1, fpout1);
```

```
/* Get the current value of the file-position pointer */
 fp = ftell(fpin);
* Subroutine write asc2 header()
* Description:
   This subroutine writes the header information in the asc2 format output files. Each asc2
    file contains the IRIGB times, maximum loads (Vmax), and minimum loads (Vmin) for
    each input channel in the input file.
void write asc2 header()
 int
          i, j;
 char
          temp name[] = "
 for (i = 0; i < num chans; i++)
   bzero((char *) (&temp name), sizeof(temp name));
   if (do calc[i] == TRUE)
    strncpy(temp name, chan name[i], 13);
    fprintf(fp_sigma_txt[i], "format asc 2 .1
    fprintf(fp sigma txt[i], "nChans
                                         1\n'');
    fprintf(fp sigma txt[i], "names
    fprintf(fp sigma txt[i], "%13s", temp name);
    fprintf(fp sigma txt[i], "\n");
    fprintf(fp sigma txt[i], "data001 \n");
/**********************************
* Subroutine skip data()
* Description:
   This subroutine reads data blocks from the input file until the start taxiing time is reached.
    It positions the file pointer to the start taxiing time. It also calculates the time interval
    between two adjacent data points to figure out the number of data blocks in 1 minute.
```

```
*********************************
void skip data()
          i, j, k, offset;
 int
          delta t, num buf;
 float
 /* Check if the start taxiing time is reached */
 for (i = 0; i < num data blocks; i++)
   fread(&data read[i], data buff size, 1, fpin);
   if (data read[i].irig time >= starting time)
    /* Read irigb time and data */
    data write1.irig time = data read[i].irig time;
    fwrite(&data write1, data buff size, 1, fpout1);
    break;
 /* Move the file pointer to the start taxiing time */
 if (i == 0)
   fread(&data read[1], data buff size, 1, fpin);
   offset = -2 * data buff size;
 else
   offset = -data buff size;
 /* Calculate the time interval between 2 adjacent data points */
 delta t = (data read[1].irig time - data read[0].irig time) / 10000.0;
 /* Calculate the number of data blocks containing in 1 minute (60 sec) */
 num buf = NUM SECONDS / delta t;
 normal buf = (int) num buf;
 /* Move the file position indicator to the start taxiing time */
 fseek(fpin, offset, SEEK CUR);
```

```
}
/**********************
* Subroutine read data()
* Description:
  This subroutine determines the number of data blocks to read into data read buffers.
  After each reading, it checks to see if the drop or stop time is reached. If yes, it sets the
   last data read indicator to TRUE and determines the buffer size for the last data read. If
   no, it sets the buffer size and move the file pointer to the right position for the next data
*
   read.
void read data()
 int
          i, count, offset;
 num read++;
 num blocks = 0;
 bzero((char *) (&data write1), sizeof(data write1));
 /* Determine the number of data blocks to read */
 if (first time == TRUE)
   count = normal buf + 2;
 else
   count = normal buf + 1;
 for (i = 0; i < count; i++)
   /* Read data */
   fread(&data read[i], data buff size, 1, fpin);
   num blocks++;
   /* Check if the drop or stop time is reached */
   if (data_read[i].irig_time >= drop_time)
     /* Indicate the last data read */
     last data read = TRUE;
```

```
time deltaa = data read[i].irig time;
     data write1.irig time = data read[i].irig time;
     buf size = i+1;
     break;
 /* Check if this is the last data read */
 if (last data read == FALSE)
   buf size = count-1;
   time deltaa = data read[buf size-1].irig_time;
   data write1.irig time = data read[buf size-1].irig time;
   /* Move the file pointer to the right position for next data read */
   offset = -data buff size;
   fseek(fpin, offset, SEEK CUR);
}
/****************************
* Subroutine determine max min()
* Description:
* This subroutine determines Vmax and Vmin loads for the current data read.
* V_i = V_{max} if V_i > V_{i-1} and V_i > V_{i+1}
* Vi = Vmin if Vi < Vi-1 and Vi < Vi+1
* In cases that Vi-1 < Vi < Vi+1 or Vi-1 > Vi > Vi+1, Vi is definitely not Vmax nor Vmin.
   In these special cases, comparisons will continue beyond i+1 data point. When a Vmax
   or Vmin is found, its IRIGB time and its value are written into the asc2 file and also
   stored in two dimensional min max value arrays to be used later for calculating
   crack growths.
void determine max min()
 char
          ch name[] = "
          save euc[MAXBUFS];
 float
          calc stress, min max;
 float
          i, j, k, l, index, start index, cur index;
 int
          max min found;
 short
 /* Reset indicators and variables */
```

```
bzero((char *) (&processed done), sizeof(processed done));
bzero((char *) (&min max value), sizeof(min max value));
bzero((char *) (&min max time), sizeof(min max time));
/* For each channel */
for (j = 0; j < num chans; j++)
 bzero((char *) (&temp euc), sizeof(temp euc));
 /* Load data into working temp euc buffers */
 if (do calc[j] == TRUE)
   if (last data read == FALSE)
     for (i = 0; i < (buf size+1); i++)
       temp euc[i] = data read[i].euc data[i];
   else
     for (i = 0; i < buf size; i++)
       temp euc[i] = data read[i].euc data[i];
   /* Determine max loads Vmax and min loads Vmin */
   i = 0;
   index = 0;
   while ((i < buf size) && (processed done[j] == FALSE))
     if (i == 0)
       if (first_time == TRUE)
         1 = 0;
         if (\text{temp euc}[i] < \text{temp euc}[i+1])
          prev_type[j] = MIN;
```

```
prev value[j] = temp euc[i];
 min max value[j][1] = temp euc[i];
 min_max_time[j][1] = data_read[i].irig_time;
 index = i+1;
else if (temp euc[i] > temp euc[i+1])
 prev type[j] = MAX;
 prev value[j] = temp euc[i];
 min max value[j][1] = temp euc[i];
 min max time[j][1] = data read[i].irig time;
 index = i+1;
else
 max min found = FALSE;
 for (k = (i+1); k < buf size; k++)
   if (\text{temp euc}[k] > \text{temp euc}[k+1])
     max min found = TRUE;
     prev type[j] = MAX;
     prev value[j] = temp euc[k];
     min max value[j][l] = temp euc[k];
     min max time[j][l] = data read[k].irig time;
     index = k+1;
     break;
   else if (temp euc[k] < temp euc[k+1])
     max min found = TRUE;
     prev type[j] = MIN;
     prev value[j] = temp euc[k];
     min max value[j][l] = temp euc[k];
     min max time[j][l] = data read[k].irig time;
     index = k+1;
     break;
 if (max min found == FALSE)
   printf("\nChan %s has the same data value of %15.2f!!!\n",
          chan name[i], temp euc[1]);
   printf("crackGrowth program terminated!!!\n");
```

```
exit (0);
 } /* if (temp_euc[i] < temp_euc[i+1]) */</pre>
} /* if (first time == TRUE) */
else
 1 = 1;
 min_max_value[j][0] = last_data[j];
 min_max_time[j][0] = last_data_time[j];
 if ((\text{prev value}[j] == \text{end value}[j]) \&\& (\text{prev type}[j] == \text{end type}[j]))
   if (temp_euc[i] < temp_euc[i+1])
     if (prev_type[j] == MAX)
       prev type[i] = MIN;
       prev_value[j] = temp_euc[i];
       min max value[j][1] = temp euc[i];
       min_max_time[j][l] = data_read[i].irig_time;
       index = i+1;
     else
       for (k = (i+1); k < buf size; k++)
         if (temp_euc[k] > temp_euc[k+1])
           prev type[j] = MAX;
           prev_value[j] = temp_euc[k];
           min max value[j][l] = temp euc[k];
           min_max_time[j][l] = data_read[k].irig_time;
           index = k+1;
           break;
   else
     if (prev_type[j] == MIN)
       prev_type[j] = MAX;
       prev_value[j] = temp_euc[i];
       min_max_value[j][l] = temp_euc[i];
       min_max_time[j][l] = data_read[i].irig_time;
```

```
index = i+1;
   else
    for (k = (i+1); k < buf_size; k++)
      if (temp_euc[k] < temp_euc[k+1])
        prev_type[j] = MIN;
        prev_value[j] = temp_euc[k];
        min max value[j][l] = temp euc[k];
        min max time[j][l] = data read[k].irig time;
        index = k+1;
        break;
     } /* else */
}
else
 if(temp_euc[i] < temp_euc[i+1])
   if (temp_euc[i] < end_value[j])</pre>
    prev_type[j] = MIN;
    prev_value[j] = temp_euc[i];
    min_max_value[j][l] = temp_euc[i];
    min max time[j][l] = data read[i].irig time;
    index = i+1;
   else
    for (k = (i+1); k < buf size; k++)
      if (temp_euc[k] > temp_euc[k+1])
        prev_type[j] = MAX;
        prev value[j] = temp euc[k];
        min_max_value[j][l] = temp_euc[k];
        min max time[j][l] = data read[k].irig time;
        index = k+1;
        break;
```

```
else
      if (temp euc[i] > end value[j])
        prev_type[j] = MAX;
        prev_value[j] = temp_euc[i];
        min_max_value[j][l] = temp euc[i];
        min max time[j][l] = data read[i].irig time;
        index = i+1;
      }
      else
        for (k = (i+1); k < buf size; k++)
         if (temp_euc[k] < temp_euc[k+1])
           prev_type[j] = MIN;
           prev value[j] = temp euc[k];
           min_max_value[j][l] = temp_euc[k];
           min max time[j][l] = data read[k].irig time;
           index = k+1;
           break;
         } /* first time == FALSE */
 fprintf(fp sigma txt[j], "\%9.3f \%8.2f \n",
       (float) min_max_time[j][1]/10000.0, min_max_value[j][1]);
 1++;
else if (i \le (buf size-2))
 if (\text{temp euc}[i] > \text{temp euc}[i+1])
   if (prev type[j] == MIN)
    prev type[j] = MAX;
    prev_value[j] = temp_euc[i];
    min max value[j][1] = temp euc[i];
    min max time[j][l] = data read[i].irig time;
    index = i+1;
```

```
(float) min max time[j][1]/10000.0, min max value[j][1]);
 1++;
else
if((i+1) \ge (buf\_size-1))
 processed done[j] = TRUE;
 if (last data read == TRUE)
   if (min_max_value[j][l-1] != temp_euc[buf_size-1])
    min_max_value[j][l] = temp_euc[buf_size-1];
    min_max_time[j][l] = data_read[buf_size-1].irig_time;
    fprintf(fp sigma txt[i], "%9.3f %8.2f \n",
          (float) min_max_time[j][1]/10000.0, min_max_value[j][1]);
    1++;
 else
   if (temp_euc[buf_size-1] < temp_euc[buf_size])
    prev_type[j] = MIN;
    end type[i] = MIN;
    prev_value[j] = temp_euc[buf_size-1];
    end value[j] = temp euc[buf size-1];
    min max value[j][1] = temp euc[buf size-1];
    min max time[j][l] = data read[buf size-1].irig time;
    (float) min max time[j][1]/10000.0, min max value[j][1]);
    1++;
   else
    end type[i] = NONE;
    end_value[j] = temp_euc[buf_size-1];
   }
 index = buf size;
else
```

```
for (k = (i+1); k < buf size; k++)
 if (k < (buf\_size-1))
   if (\text{temp\_euc}[k] < \text{temp\_euc}[k+1])
     prev_type[j] = MIN;
     min max value[j][l] = temp euc[k];
     min_max_time[j][l] = data_read[k].irig_time;
     fprintf(fp_sigma_txt[j], "%9.3f %8.2f \n",
          (float) min max time[j][1]/10000.0, min max value[j][1]);
     1++;
     index = k+1;
     break;
 }
 else
   processed done[j] = TRUE;
   if (last data read == TRUE)
     if (min max value[j][l-1] != temp euc[buf size-1])
       min max value[j][1] = temp euc[buf size-1];
       min max time[j][l] = data read[buf size-1].irig time;
       fprintf(fp sigma txt[i], "%9.3f %8.2f \n",
             (float) min max time[j][1]/10000.0, min max value[j][1]);
       1++;
   else
     if (temp euc[buf size-1] < temp euc[buf size])
       prev_type[j] = MIN;
       end type[j] = MIN;
       prev_value[j] = temp_euc[buf_size-1];
       end value[j] = temp euc[buf size-1];
       min max value[j][1] = temp euc[buf size-1];
       min_max_time[j][l] = data_read[buf size-1].irig time;
       fprintf(fp sigma txt[j], "%9.3f %8.2f \n",
             (float) min max time[j][1]/10000.0, min max value[j][1]);
       1++;
     else
```

```
end type[j] = NONE;
           end_value[j] = temp_euc[buf_size-1];
        index = buf_size;
else if (temp_euc[i] < temp_euc[i+1])
 if (prev_type[j] == MAX)
   prev_type[j] = MIN;
   prev value[j] = temp euc[i];
   min_max_value[j][l] = temp_euc[i];
   min max time[j][l] = data read[i].irig time;
   (float) min max time[j][1]/10000.0, min max value[j][1]);
   index = i+1;
   1++;
   }
   else
    if((i+1) >= (buf size-1))
      processed done[j] = TRUE;
      if (last data read == TRUE)
        if (min_max_value[j][l-1] != temp_euc[buf_size-1])
         min_max_value[j][l] = temp_euc[buf_size-1];
         min_max_time[j][l] = data_read[buf_size-1].irig_time;
         fprintf(fp_sigma_txt[j], " %9.3f  %8.2f \n",
               (float) min_max_time[j][1]/10000.0, min_max_value[j][1]);
         1++;
      else
        if (temp_euc[buf_size-1] > temp_euc[buf_size])
         prev_type[j] = MAX;
```

```
end type[j] = MAX;
     prev value[j] = temp euc[buf size-1];
     end_value[j] = temp_euc[buf_size-1];
     min max value[j][1] = temp euc[buf size-1];
     min_max_time[j][l] = data_read[buf_size-1].irig_time;
     (float) min_max_time[j][1]/10000.0, min_max_value[j][1]);
     1++;
   else
     end type[j] = NONE;
     end_value[j] = temp_euc[buf_size-1];
 index = buf_size;
else
 for (k = (i+1); k < buf_size; k++)
   if (k < (buf size-1))
    if (temp_euc[k] > temp_euc[k+1])
      prev_type[j] = MAX;
      prev value[j] = temp euc[k];
      min_max_value[j][l] = temp_euc[k];
      min max time[j][l] = data read[k].irig time;
      fprintf(fp sigma txt[j], "\%9.3f \%8.2f \n",
             (float) min max time[j][1]/10000.0, min max value[j][1]);
      1++;
      index = k+1;
      break;
   else
     processed done[j] = TRUE;
     if (last data read == TRUE)
      if (min_max_value[j][l-1] != temp_euc[buf_size-1])
        min_max_value[j][l] = temp_euc[buf_size-1];
        min_max_time[j][l] = data_read[buf_size-1].irig_time;
```

```
fprintf(fp sigma txt[j], "\%9.3f \%8.2f \n",
                   (float) min max time[j][1]/10000.0, min max value[j][1]);
             1++;
          } /* if (last_data_read == TRUE) */
          else
            if (temp_euc[buf_size-1] > temp_euc[buf_size])
             prev_type[j] = MAX;
             end type[j] = MAX;
             prev value[j] = temp euc[buf size-1];
             end_value[j] = temp_euc[buf_size-1];
             min_max_value[j][l] = temp_euc[buf_size-1];
             min_max_time[j][1] = data_read[buf_size-1].irig_time;
              (float) min max time[j][1]/10000.0, min max value[j][1]);
            } /* if (temp euc[buf size-1] > temp euc[buf size]) */
            else
             end type[j] = NONE;
              end value[j] = temp euc[buf size-1];
          } /* if (last data read != TRUE) */
          index = buf size;
 else /* temp_euc[i] = temp_euc[i+1] */
   index = i + 1;
else if (i == (buf size-1))
 processed done[j] = TRUE;
 if (last data read == TRUE)
   if (min max value[j][l-1] != temp euc[buf size-1])
     min max value[j][1] = temp euc[buf size-1];
     min_max_time[j][l] = data_read[buf_size-1].irig_time;
```

```
(float) min max time[j][1]/10000.0, min max value[j][1]);
   1++;
} /* if (last_data_read == TRUE) */
else
 if (temp euc[i] < temp euc[i-1])
   if(temp_euc[i] < temp_euc[i+1])
    prev type[j] = MIN;
    prev_value[j] = temp_euc[i];
    end type[j] = MIN;
    end_value[j] = temp_euc[i];
    min_max_value[j][l] = temp_euc[i];
    min max time[j][l] = data read[i].irig time;
    (float) min max time[j][1]/10000.0, min max value[j][1]);
    1++;
   }
   else
    end type[j] = NONE;
    end value[j] = temp euc[i];
 }
 else
   if (\text{temp euc}[i] > \text{temp euc}[i+1])
    prev type[j] = MAX;
    prev_value[j] = temp_euc[i];
    end type[j] = MAX;
    end value[i] = temp euc[i];
    min_max_value[j][l] = temp_euc[i];
    min max time[j][l] = data read[i].irig time;
     fprintf(fp\_sigma\_txt[j], "\%9.3f \%8.2f \n",
          (float) min max time[j][1]/10000.0, min max value[j][1]);
    1++;
   else
    end type[j] = NONE;
     end value[j] = temp euc[i];
```

```
} /* if (last data read != TRUE) */
        index = buf size;
      if (min max value[i][1-1] \leq 0.0)
        strncpy(ch name, chan name[i], 10);
        printf("\nChan %10s has BAD data %9.2f!! ", ch_name, min_max_value[j][l-1]);
        printf("at Irigb time = \%9.3f\n\n", (float) min_max_time[j][l-1]/10000.0);
        printf("crackGrowth program terminated!!!\n");
        exit(0);
      i = index;
     write index[j] = 1;
     last_data[j] = min max value[i][1-1];
     last data time[j] = min max time[j][1-1];
   \} /* for ( j = 0; j < num chans; j++) */
* Subroutine calculate deltaa()
* Description:
  This subroutine uses the Vmax and Vmin loads determined in subroutine
   determine max min() to calculate half cycle crack growth delta a. It sums up all
   calculated delta a to get the total crack growth size. It also determines the worst half
   cycle ratio Ri = load min / load max during the period between takeoff run and cruise
   power. The worst half cycle Vmax load will be used in calculating the number of
   operational flights.
void calculate deltaa()
 int
          i, j, k, l;
         Ai 1, pow Kmax, pow Ri, sqrt value, double const;
 double
          Ri, Kmax, float sum deltaa;
 float
          load max, load min, stress;
 float
 short
          cal deltaa;
 bzero((char *) (&deltaa), sizeof(deltaa));
 double const = 10000.0;
```

```
/* For each channel */
for (j = 0; j < \text{num chans}; j++)
 if (do\_calc[j] == TRUE)
   if (first_time == TRUE)
     Ai_1 = apc[j];
     sum a[j] = apc[j];
   else
     Ai_1 = sum_a[j];
   for (i = 1; i < write index[i]; i++)
     cal deltaa = FALSE;
     /* Determine the Vmax and Vmin in this half cycle */
     if (min max value[j][i-1] < min max value[j][i])
       load min = min max value[j][i-1];
       load max = min max value[i][i];
       cal deltaa = TRUE;
     else if (min max value[i][i-1] > min max value[i][i])
       load min = min max value[j][i];
       load max = min max value[j][i-1];
       cal deltaa = TRUE;
     if (cal deltaa == TRUE)
       Ri = load min / load max;
       /* Add the previous crack growth delta a to Ai 1 */
       Ai 1 += deltaa[i][i-1];
       /* Convert load into stress */
```

```
stress = stress coef[j]*load max;
       /* Calculate crack growth delta a */
       sqrt value = sqrt((double) PI*Ai 1/Q);
       Kmax = A*Mk*stress*(float) sqrt_value;
       pow Kmax = pow((double) Kmax, (double) m[j]);
       pow Ri = pow((double) (1.0-Ri), (double) n[j]);
       deltaa[i][i] = C OVER 2[i] * pow Kmax * pow Ri;
      /* Add the current crack growth to the sum of delta a */
       sum deltaa[j] += deltaa[j][i];
       sum a[j] += deltaa[j][i];
       /* Determine the worst half cycle */
       if ((min max time[j][i-1] >= takeoff time) &&
          (min max time[j][i-1] <= cruise time))
        if (Ri < Ri min[j])
          Ri min[i] = Ri;
          Vmax[j] = load max;
          Vmin[j] = load min;
          Tmax[j] = min max time[j][i-1];
     } /* if (cal deltaa == TRUE) */
   float sum deltaa = (float) double const * sum deltaa[j];
   data write1.euc data[i] = double const * sum deltaa[j];
  } /* if (do calc[i] == TRUE) */
\} /* for ( j = 0; j < num chans; j++) */
/* Write data into output file */
fwrite(&data write1, data buff size, 1, fpout1);
if (first time == TRUE)
 first time = FALSE;
```

```
* Subroutine calculate flights()
* Description:
    This subroutine uses the worst half cycle Vmax for calculating the number of operational
    flights based on the first flight load data.
void calculate flights()
 int
           i, j;
           real flight, remain;
 float
 double pow f1, pow a;
 for (j = 0; j < num chans; j++)
   if(do\_calc[j] == TRUE)
     f[j] = Vmax[j] / Vstar[j];
     pow f1 = pow((double) f[i], (double) (m[i]-2.0));
     numerator[j] = 1.0 - pow f1;
     pow a = pow((double) (1.0 + (sum deltaa[j]/apc[j])), (double) (1.0-(m[j]/2.0));
     denominator[j] = 1.0 - pow a;
     real flight = numerator[j]/denominator[j];
     remain = real flight - (int) real flight;
     if (remain \geq 0.5)
       int flight[j] = (int) real flight + 1;
     else
       int flight[j] = (int) real flight;
```

```
/*********************************

* Subroutine generate_summary()

* Description:

* This subroutine generates a summary for all channels in the input file. The summary

* contains the size of total crack growth, the number of operational flights, the operational

* load factor, the worst half cycle Vmax, Vmin, and its IRIGB time. Additionally, the
```

```
numerator and the denominator that are used to calculate the number of operational
   flights are also included in the summary.
*******************************
void generate summary()
 int
         i, j;
 char
         name[NAMES SIZE];
 fwrite("B-52B hooks
                       Crack Growth Flights
                                                    Vmax
                                                             Vmin
                                                                      Irigb time\n\n",
  strlen("B-52B hooks
                       Crack Growth Flights f
                                                                      Irigb time\n'"),
                                                    Vmax
                                                             Vmin
         1, fpout2);
 for (j = 0; j < num chans; j++)
   if(do\_calc[j] == TRUE)
    strncpy(name, chan name[j], NAMES_SIZE);
     fprintf(fpout2, "%s", name);
    fprintf(fpout2, "%10.4e ", sum_deltaa[j]);
    fprintf(fpout2, "%6d ", int_flight[j]);
    fprintf(fpout2, " %7.4f ", f[j]);
    fprintf(fpout2, " %9.2f ", Vmax[j]);
    fprintf(fpout2, "%9.2f ", Vmin[j]);
    fprintf(fpout2, "%9.3f\n", (float) Tmax[j]/10000.0);
 }
 fwrite("\n\nB-52B hooks
                            Numerator
                                         Denominator\n\n",
  strlen("\n\nB-52B hooks
                                         Denominator\n', 1, fpout2);
                            Numerator
 for (j = 0; j < num chans; j++)
   if (do \ calc[j] == TRUE)
    strncpy(name, chan name[j], NAMES SIZE);
    fprintf(fpout2, "%s", name);
    fprintf(fpout2, "%10.4e ", numerator[j]);
     fprintf(fpout2, "%10.4e\n", denominator[j]);
   }
 }
```

APPENDIX C MATERIAL PROPERTIES

Material properties of B-52B pylon hooks and Pegasus adapter pylon hooks are listed in Table C1 and Table C2.

Table C1. Material properties of B-52B pylon hooks and Pegasus adapter pylon hooks.

Component	Material	σ_U ksi	σ _γ ksi	$ au_U$ ksi	K_{IC} ksi $\sqrt{\text{in.}}$	$\frac{C}{\text{cycle}} \left(\text{ksi} \sqrt{\text{in.}} \right)^{-m}$	m	n
B-52B front hook	Inconel 718*	175	145	135	125	0.922×10 ⁻¹¹	3.60	2.16
B-52B rear hooks	AMAX MP35N^	250	235	141	124	2.944×10 ⁻¹¹	3.24	1.69
Pegasus hooks	AMAX MP35N^	250	235	141	124	2.944×10^{-11}	3.24	1.69

^{*} Inconel 718 is a registered trademark of Huntington Alloy Products Division, International Nickel Company, West Virginia.

Table C2. Material properties of Inconel 718 and AMAX MP35Nalloys.

Material	E , lb/in^2	G, lb/in ²	ν	ρ , lb/in ³	α, in/in-°F
Inconel 718	29.60×10^6			0.297	6.40×10^6
AMAX MP35N	34.05×10^6	11.74×10^6	0.39	0.322	7.10×10^6

 $^{^{\}wedge}\,AMAX\,MP35N$ is a trademark of SPS Technologies, Inc., Jenkintown, Pennsylvania.

FIGURES

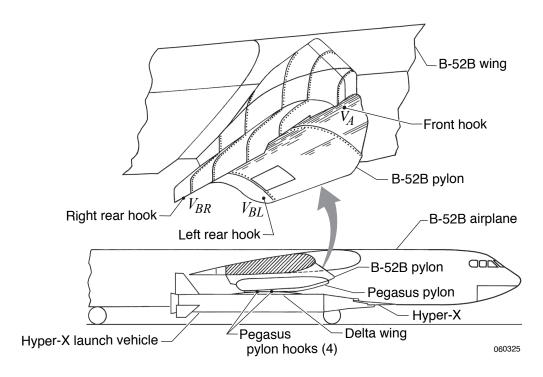


Figure 1. The B-52B airplane carrying the winged Pegasus rocket/X-43 systems (40,000 lb).

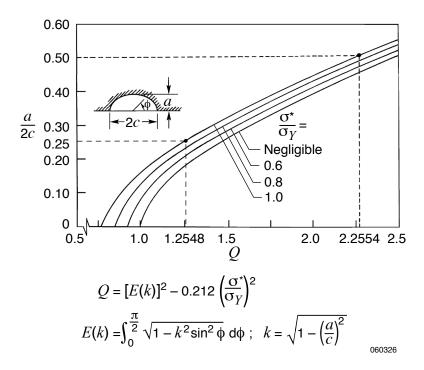


Figure 2. Surface flaw shape and plasticity factor for semi-elliptic surface cracks.

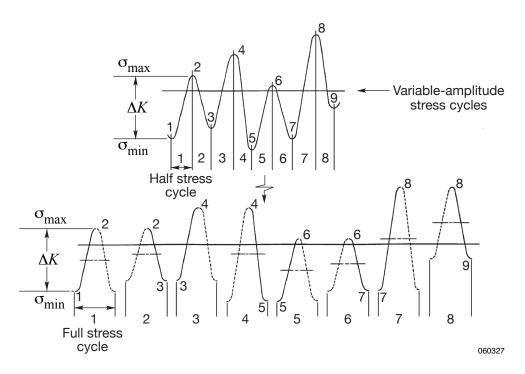


Figure 3. Resolution of random stress cycles into half stress cycles of different stress ranges.

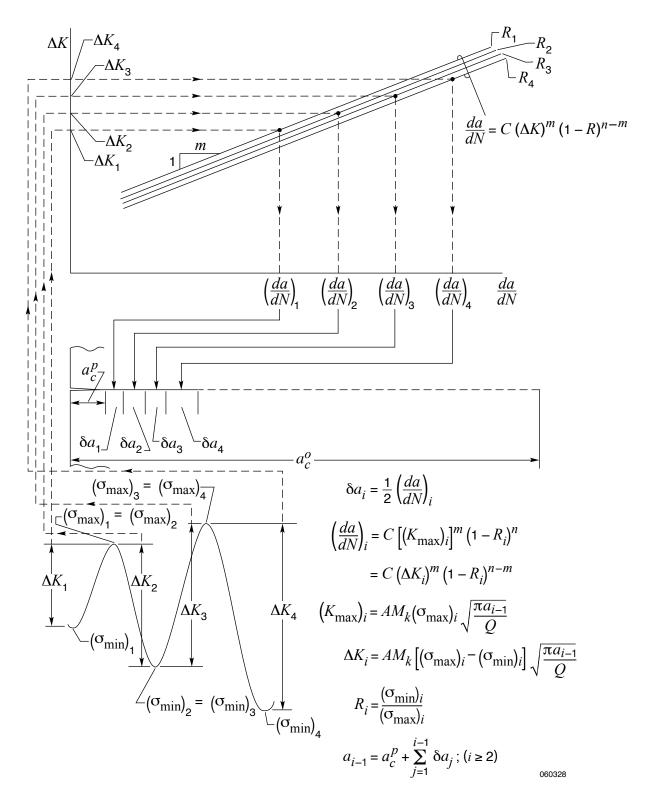


Figure 4. Graphic evaluation of crack growths caused by random loading spectrum using the half-cycle theory.

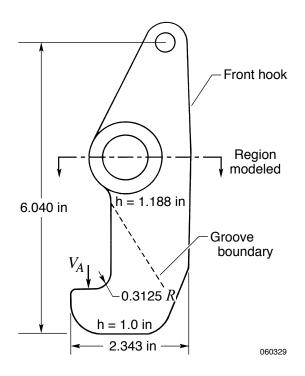


Figure 5. Geometry of B-52B pylon front hook.

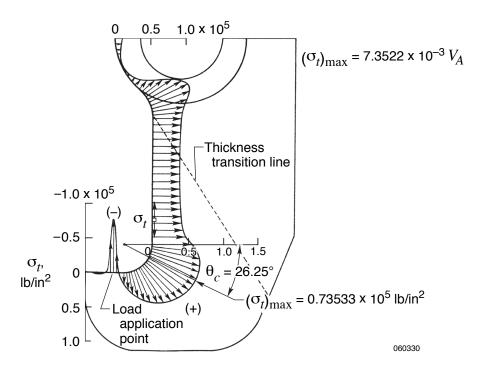


Figure 6. Distribution of tangential stress, σ_t , along the inner boundary of the B-52B pylon front hook; V_A =10,000 lb.

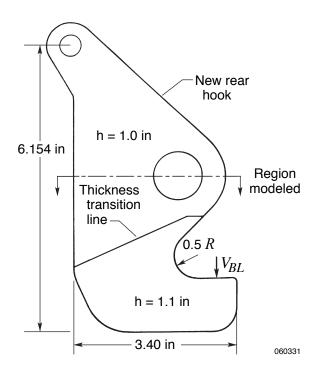


Figure 7. Geometry of the B-52B pylon rear hook.

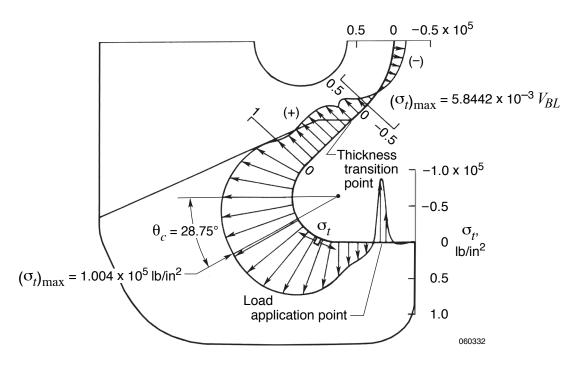


Figure 8. Distribtuion of tangential stress, σ_t , along the inner boundary of a typical B-52B pylon rear hook; V_{BL} =17,179.53 lb.

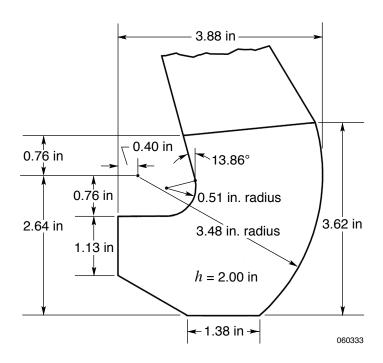


Figure 9. Geometry of the Pegasus pylon hook.

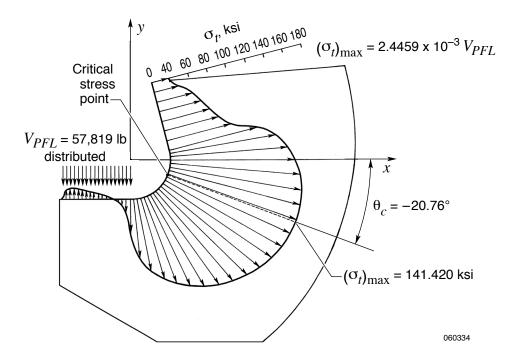


Figure 10. Distribution of tangential stress, σ_t , along the inner boundary of a typical Pegasus pylon hook; V_{PFL} =57,819 lb.

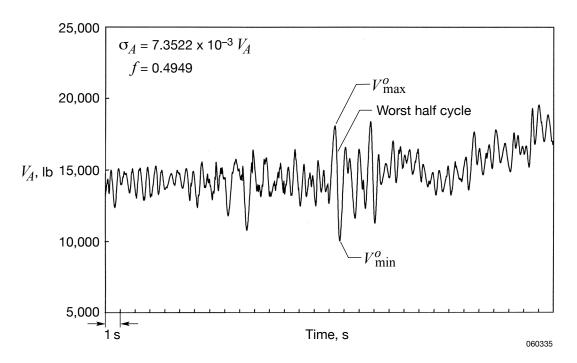


Figure 11. Loading spectrum of the B-52B front hook (VA) carrying the Hyper-X launching vehicle during takeoff.

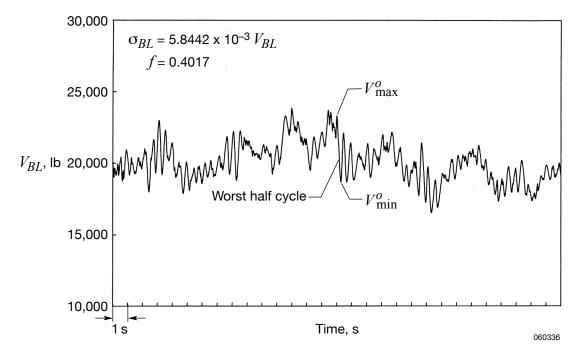


Figure 12. Loading spectrum of the B-52B rear left hook (VBL) carrying the Hyper-X launch vehicle during takeoff.

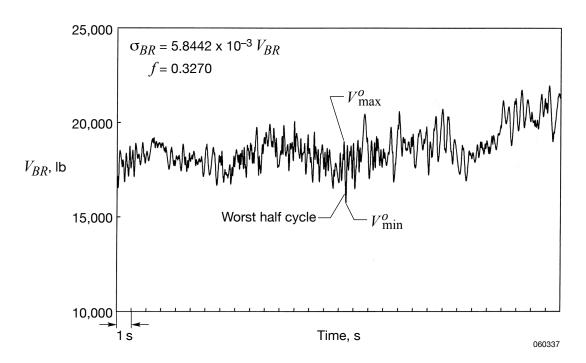


Figure 13. Loading spectrum of the B-52B rear right hook (VBR) carrying the Hyper-X launching vehicle during takeoff.

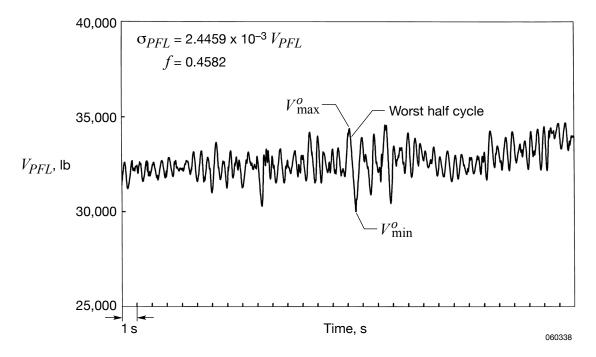


Figure 14. Loading spectrum of the Pegasus pylon front left hook (VPFL) carrying the Hyper-X launching vehicle during takeoff.

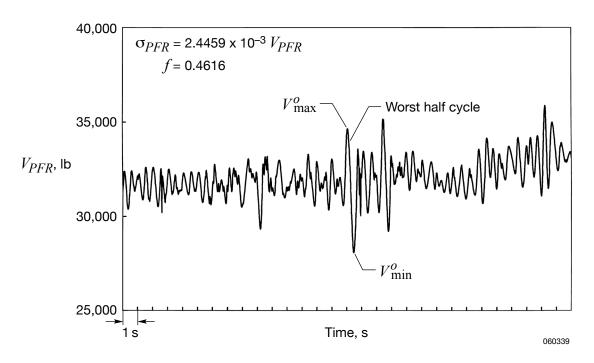


Figure 15. Loading spectrum of the Pegasus pylon front right hook (VPFR) carrying the Hyper-X launching vehicle during takeoff.

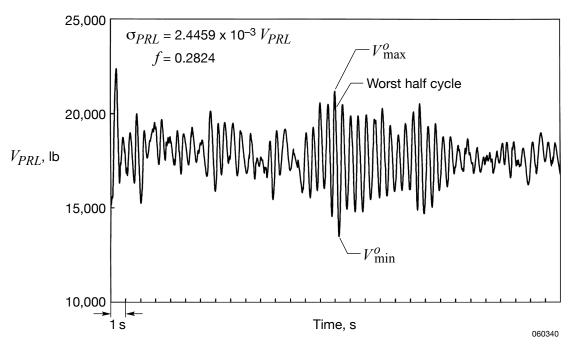


Figure 16. Loading spectrum of the Pegasus pylon rear left hook (VPRL) carrying Hyper-X launching vehicle during takeoff.

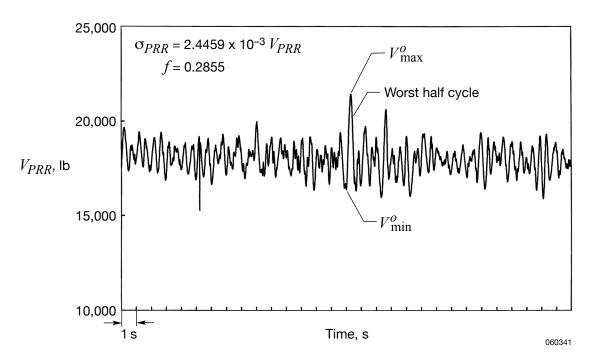


Figure 17. Loading spectrum of the Pegasus pylon rear right hook (VPRR) carring the Hyper-X launching vehicle during takeoff.

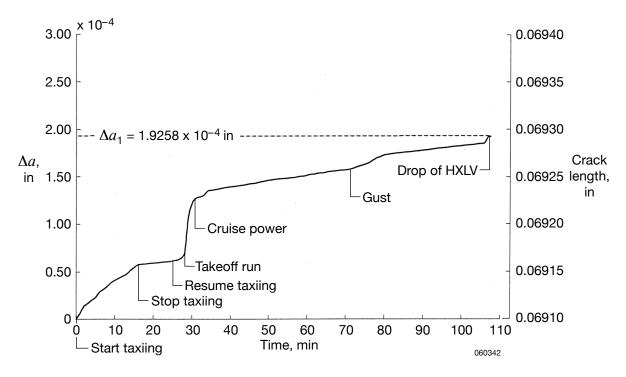


Figure 18. Crack growth curve for the B-52B front hook (VA); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

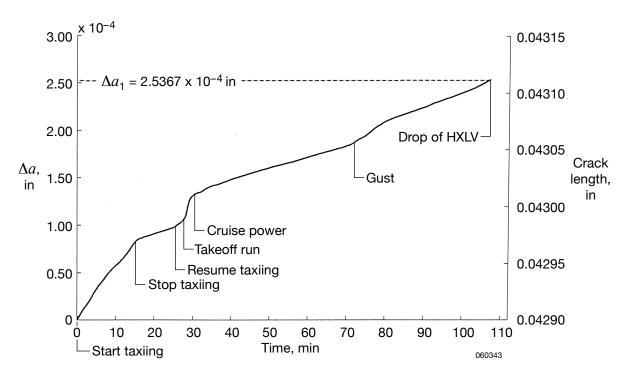


Figure 19. Crack growth curve for the B-52B rear left hook (VBL); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

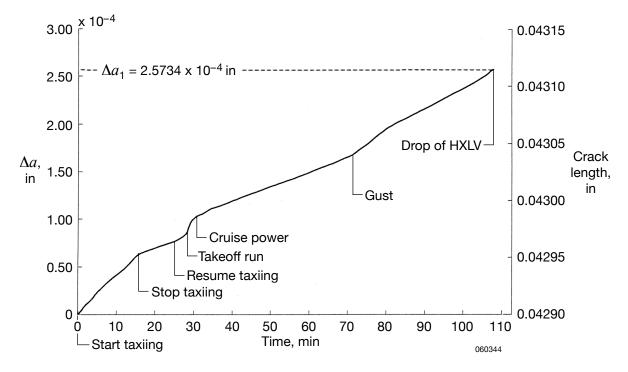


Figure 20. Crack growth curve for the B-52B rear right hook (VBR); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

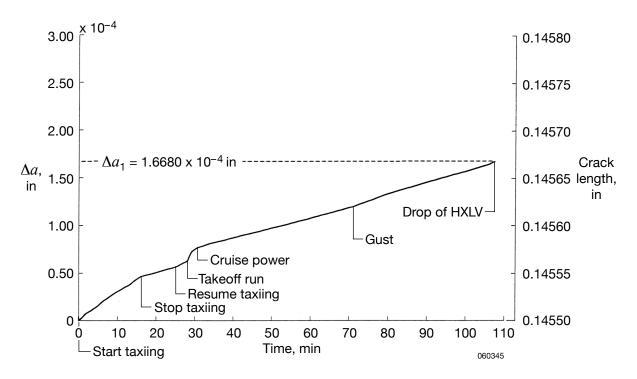


Figure 21. Crack growth curve for the Pegasus pylon front left hook (VPFL); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

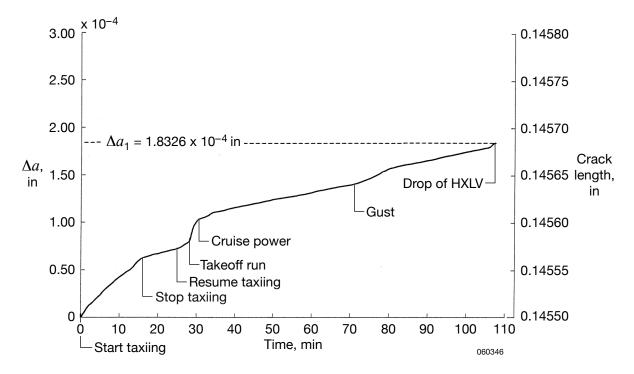


Figure 22. Crack growth curve for the Pegasus pylon front right hook (VPFR); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

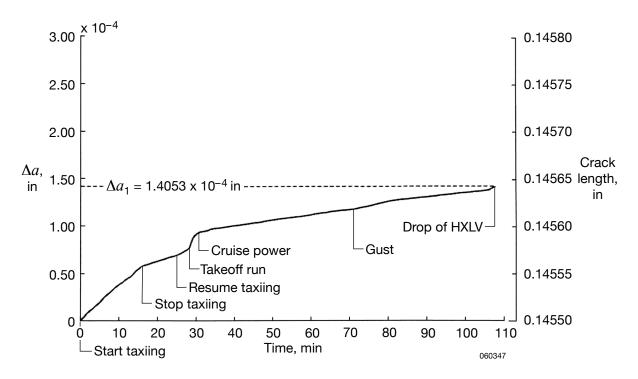


Figure 23. Crack growth curve for the Pegasus pylon rear left hook (VPRL); B-52B carrying the Hyper-X launching vehicle; air-launching flight.

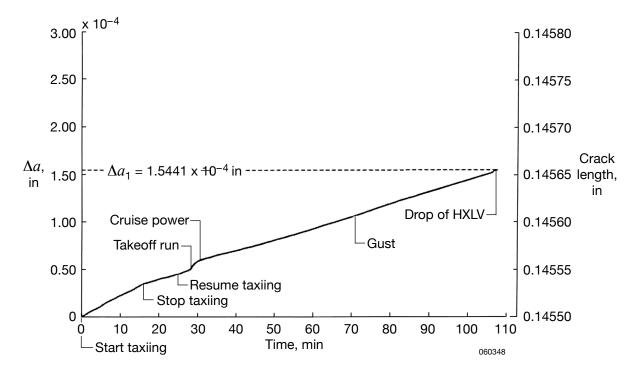


Figure 24. Crack growth curve for the Pegasus pylon rear right hook (VPRR); B-52B carrying the the Hyper-X launching vehicle; air-launching flight.

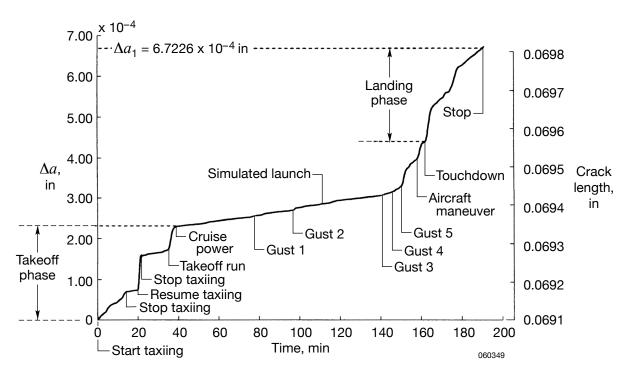


Figure 25. Crack growth curve for the Pegasus pylon front hook (VA); B-52B carrying the Hyper-X launching vehicle; captive flight.

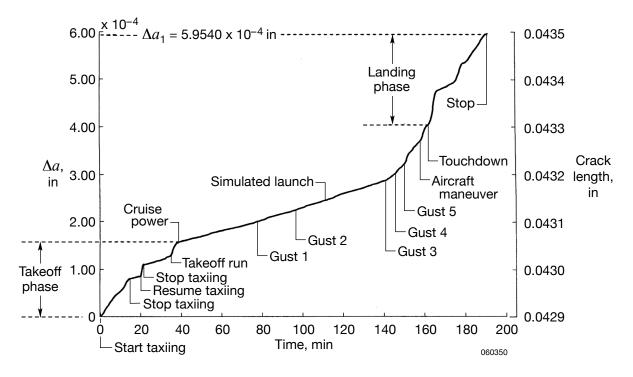


Figure 26. Crack growth curve for the B-52B rear left hook (VBL); B-52B carrying the Hyper-X launching vehicle; captive flight.

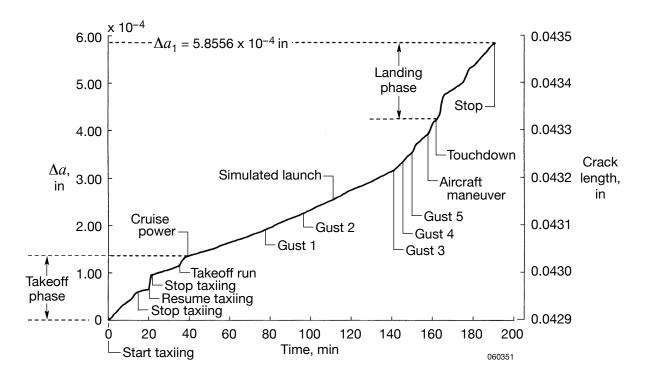


Figure 27. Crack growth curve for the B-52B rear right hook (VBR); B-52B carrying the Hyper-X launching vehicle; captive flight.

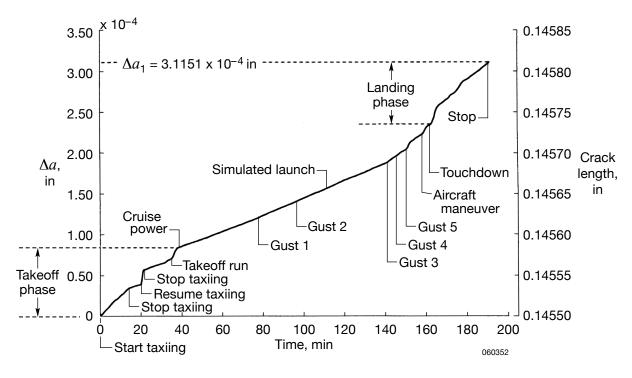


Figure 28. Crack growth curve for the Pegasus pylon front left hook (VPFL); B-52B carrying the Hyper-X launching vehicle; captive flight.

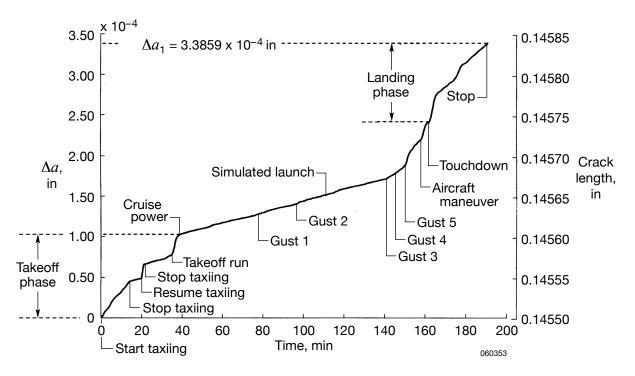


Figure 29. Crack growth curve for the Pegasus pylon front right hook (VPFR); B-52B carrying the Hyper-X launching vehicle; captive flight.

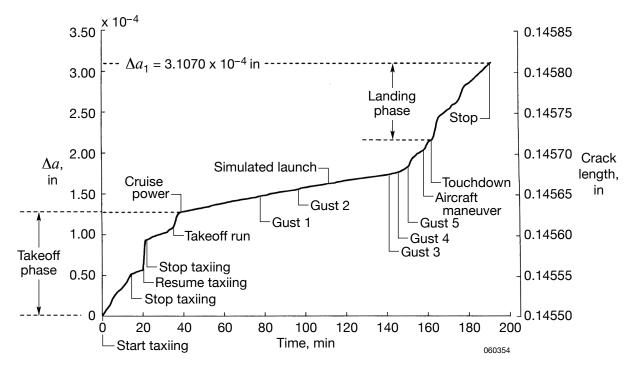


Figure 30. Crack growth curve for the Pegasus pylon rear left hook (VPRL); B-52B carrying the Hyper-X launching vehicle; captive flight.

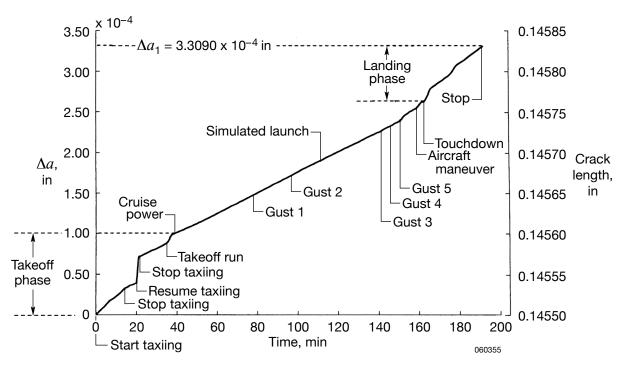


Figure 31. Crack growth curve for the Pegasus pylon rear right hook (VPRR); B-52B carrying the Hyper-X launching vehicle; captive flight.

REFERENCES

- 1. Ko, William L., A. L. Carter, W. W. Totton, and J. M. Ficke, *Application of Fracture Mechanics and Half-Cycle Method to the Prediction of Fatigue Life of B-52 Aircraft Pylon Components*, NASA TM-88277, 1989.
- 2. Ko, William L., Prediction of Service Life of Aircraft Structural Components Using the Half-Cycle Method, NASA TM-86812, 1987.
- 3. Ko, William L. and Richard Monaghan, *Practical Theories for Service Life Prediction of Critical Aerospace Structural Components*, NASA TM-4354, 1992.
- 4. Ko, William L., Richard C. Monaghan, and Raymond H. Jackson, *Practical Theories for Service Life Predictions of Critical Aerospace Structural Components*. Presented at the 4th International Conference on Structural Failure, *Product Liability and Technical Insurance*, Vienna, Austria, July 6–9, 1992. Reprinted from Rossmanith, H. P., *Structural Failure, Product Liability and Technical Insurance IV*, Elsevier Science Publishers, Amsterdam, the Netherlands, pp. 495–504, July 1993.
- 5. Ko, William L., Aging Theories for Establishing Safe Life Spans of Airborne Critical Structural Components, NASA TP-212034, 2003.
- 6. Ko, William L. and Tony Chen, Extended Aging Theories for Predictions of Safe Operational Life of Critical Airborne Structural Components, NASA TP-2006-213676, 2006.
- 7. Ko, William L. and Lawrence S. Schuster, *Stress Analyses of B-52 Pylon Hooks*, NASA TM-84924, 1985.
- 8. Ko, William L., Stress Analysis of B-52B and B-52H Air-Launching Systems Failure-Critical Structural Components, NASA TP-2005-212862, 2005.
- 9. Ko, William L., *Stress Analysis of B-52 Pylon Hooks for Carrying the X-38 Drop Test Vehicle*, NASA/TM-97-206218, 1997.
- 10. Hodgeman, Charles D., *Standard Mathematical Tables*, 11th ed., Chemical Rubber Publishing Co., Cleveland, Ohio, pg. 252, 1957.
- 11. Barrois, W. and E. L. Ripley, *Fatigue of Aircraft Structures*, The Macmillan Co., New York, 1963.
- 12. Starky, W. L. and S. M. Marco, *Effects of Complex Stress-Time Cycles on the Fatigue Properties of Metals*. Transaction of the ASME, pp. 1329–1336, August 1957.

REPORT DOCUMENTATION PAGE

Form Approved OMB No. 0704-0188

The public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Department of Defense, Washington Headquarters Services, Directorate for Information Operations and Reports (0704-0188), 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to any penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.

PLEASE DO NOT RETURN YOUR FORM TO THE ABOVE ADDRESS.

1. REPORT DATE (DD-MM-YYYY)	2. REPORT TYPE		3. DATES COVERED (From - To)	
31-01-2007	Technical Publication			
4. TITLE AND SUBTITLE			5a. CONTRACT NUMBER	
	y Into Ko Aging Theory for Aerostruct	ural		
Flight-Life Predictions			5b. GRANT NUMBER	
		5c. PRO	OGRAM ELEMENT NUMBER	
6. AUTHOR(S)			5d. PROJECT NUMBER	
Ko, William L.; Tran, Van T.; and	Chen, Tony			
	·	5e. TAS	K NUMBER	
		5f. WOF	RK UNIT NUMBER	
7. PERFORMING ORGANIZATION NA NASA Dryden Flight Research Ce P.O. Box 273	` ,	•	8. PERFORMING ORGANIZATION REPORT NUMBER	
Edwards, California 93523-0273			Н-2673	
9. SPONSORING/MONITORING AGE	NCY NAME(S) AND ADDRESS(ES)		10. SPONSORING/MONITOR'S ACRONYM(S)	
National Aeronautics and Space Administration Washington, DC 20546-0001			NASA	
<u> </u>			11. SPONSORING/MONITORING REPORT NUMBER	
			NASA/TP-2007-214608	
12. DISTRIBUTION/AVAILABILITY ST	ATEMENT			

Unclassified -- Unlimited

Subject Category 39 Availability: NASA CASI (301) 621-0390 Distribution: Standard

13. SUPPLEMENTARY NOTES

Ko, Tran, Chen, Dryden Flight Research Center

14. ABSTRACT

The half-cycle crack growth theory was incorporated into the Ko closed-form aging theory to improve accuracy in the predictions of operational flight life of failure-critical aerostructural components. A new crack growth computer program was written for reading the maximum and minimum loads of each half-cycle from the random loading spectra for crack growth calculations and generation of in-flight crack growth curves. The unified theories were then applied to calculate the number of flights (operational life) permitted for B-52B pylon hooks and Pegasus® adapter pylon hooks to carry the Hyper-X launching vehicle that air launches the X-43 Hyper-X research vehicle. A crack growth curve for each hook was generated for visual observation of the crack growth behavior during the entire air-launching or captive flight. It was found that taxiing and the takeoff run induced a major portion of the total crack growth per flight. The operational life theory presented can be applied to estimate the service life of any failure-critical structural components.

15. SUBJECT TERMS

Crack growth curves, Fatigue cracks, Half-cycle theory, Operational life predictions, Structural aging theory

16. SECURITY CLASSIFICATION OF:		ABSTRACT OF		19a. NAME OF RESPONSIBLE PERSON	
a. REPORT	b. ABSTRACT	c. THIS PAGE		PAGES	STI Help Desk (email: help@sti.nasa.gov)
1					19b. TELEPHONE NUMBER (Include area code)
U	U	U	UU	88	(301) 621-0390